



# A.I. Assisted Experiment Control and Calibration

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# **Annual Budget**



# Summary of expenditures by fiscal year (FY)\*:

	FY20 (\$k)	FY21 (\$k)	FY22 (\$k)	Totals (\$k)
a.) Funds allocated	270	270	270	810
b.) Actual Costs to date	270	270	270	810

total award for 3 years: \$810k

Mostly labor cost



\*n.b. funds come at end of fiscal year so are actually spent during the following fiscal year

#### **Motivation**



- Sensitive detectors need to be calibrated to obtain optimal resolution
- Calibrations cause a delay between data collection and analysis (weeks-months)
  - Multiple iterations are needed to converge to final set of constants

## **Main Goal:**

Dynamically adjust the controls of a sensitive detector to reduce or eliminate the need for calibration



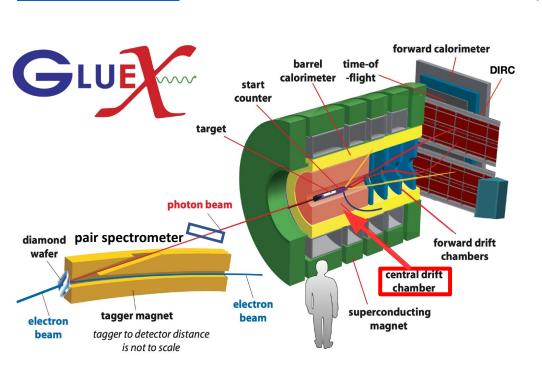


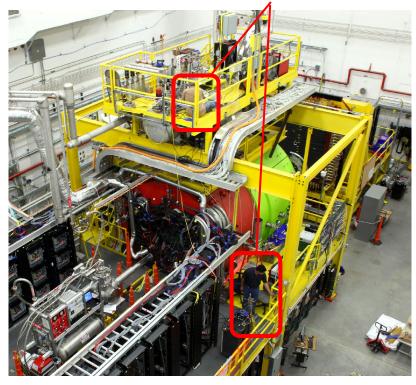
## **The GlueX Detector**



GlueX detector located in Hall D at Jefferson Lab, VA









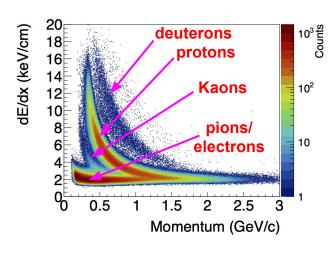
#### **The CDC** (= Central Drift Chamber)



- 1.5m long x 1.2m diameter cylinder; central hole for beam, target and start counter scintillators
- 3522 anode wires at 2125V inside 1.6cm diameter straw
- Ar/CO2 gas mix, approx. 30 Pa above atmospheric pressure
- Measures drift time and deposited charge









#### Conventional Calibration and Motivation for ML



## **Motivation: Conventional vs. Online, ML Calibration Paradigms**

#### Conventional

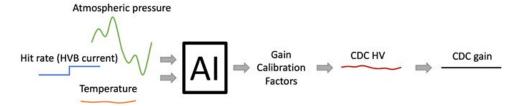
- Calibrate: calibration values iteratively, produced after the experiment
  - ~2 hour runs
- **Control**: CDC operating voltage is **fixed** at 2125 V





#### Online and ML

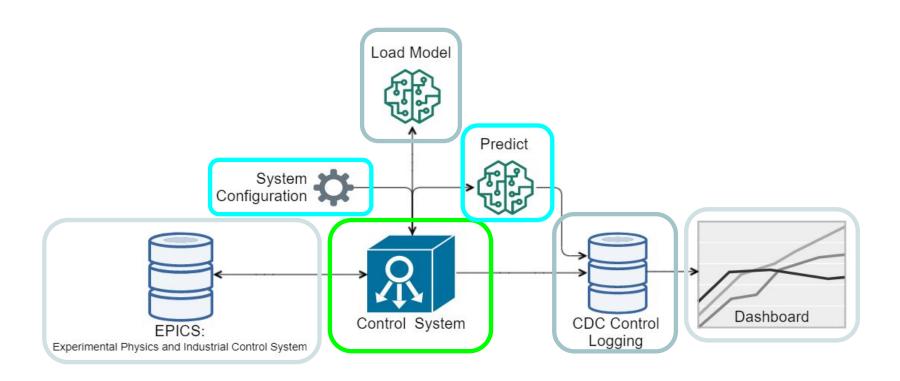
- Control: Stabilize detector response to changing environmental/experimental conditions by adjusting CDC HV
- Calibrate: online calibration values produced during the experiment





# **Integrating Al/ML into Control System**







## Fall 2021 Beam Test



- Mid-October to early November 2021
- PrimEx-η running with GlueX Detector in Hall-D
  - Run plan was to have small amount of data with Solenoid on but most with it off
- Planned to test Al system over 2 days when solenoid was on
- Background levels were improved significantly with solenoid on
  - PI's changed plan and ran with it on for ~2weeks



Atmospheric pressure did not change as much as we wanted







## Gain correction factors from conventional calibrations

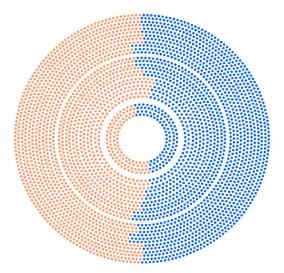




# **Automation Test with Cosmic Rays**

EXPERIMENTAL Physics Software and Computing Infrestructure

- Two weeks in March 2022
- Half of sense wires controlled by AI/ML. Other half used fixed HV
- Fully automated with AI/ML adjustments every 5 minutes
- No beam. Cosmics only.

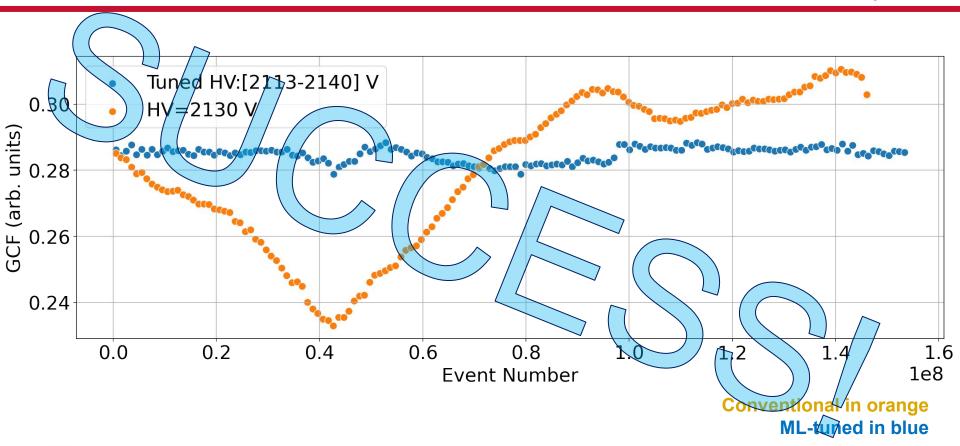






## **Cosmics Test Results**







## The Gaussian process model



## **ML Technique**

## **Gaussian Process (GP)**

- 3 features:
  - atmospheric pressure within the hall
  - **Gas temperature** within CDC
  - CDC high voltage board current a measure of luminosity
- 601 runs from 2020 and 2021 run periods
  - Pressure balanced for low, medium and high pressure
  - 80 / 20 train test split
- 1 target: the traditional Gain Correction Factor (GCF)
- GP calculates PDF over admissible functions that fit data
- GP provides the standard deviation
  - we can exploit for uncertainty quantification (UQ)
- GP kernel:
  - Radial Basis Function + White noise
  - Compared isotropic (1 length scale) and anisotropic (length scale per input variable) kernels

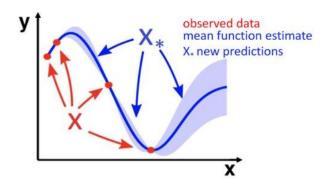


Illustration training a Gaussian process

#### Our goal was better than a 5% error

RBF kernel (length scale(s))		RMSE	Mean  % err
Isotropic (1.412)	0.97	0.002	0.8%
Anisotropic (1.4,1.17,.171)	0.97	0.002	0.8%

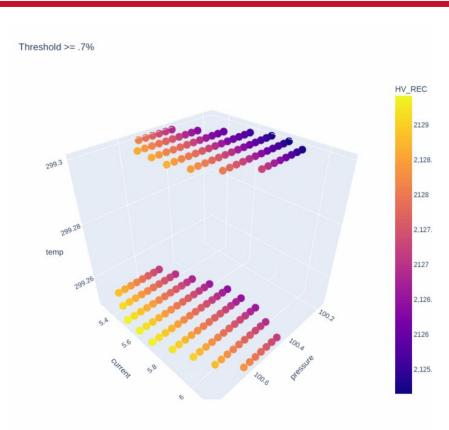


# **Uncertainty Quantification**



We created a system to automate the learning process as environmental and experimental conditions change:

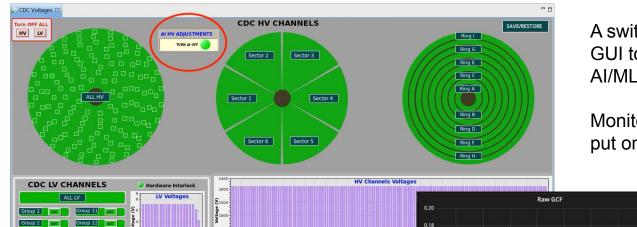
- A system that knows when it is certain and controls the experiment
- Says "I don't know" when uncertain, and collects more data and "learns"
- Online retraining, evaluation of retrained model... (future)
- Implement the retrained model that should be certain for more conditions





## **Integrating Al/ML into Standard Operations**

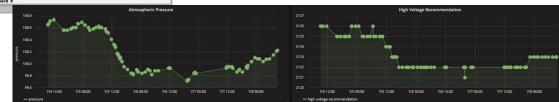




A switch was added to CDC Control GUI to allow shift takers to disable the AI/ML control completely.

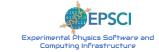
Monitoring of the entire system was put onto a Grafana server.



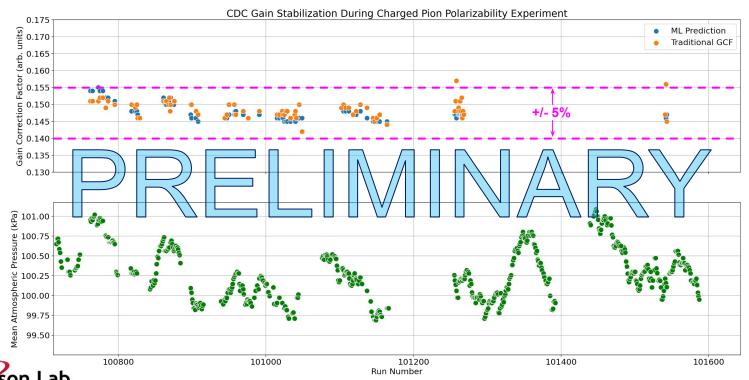




# Fully Automated System Deployed - RoboCDC

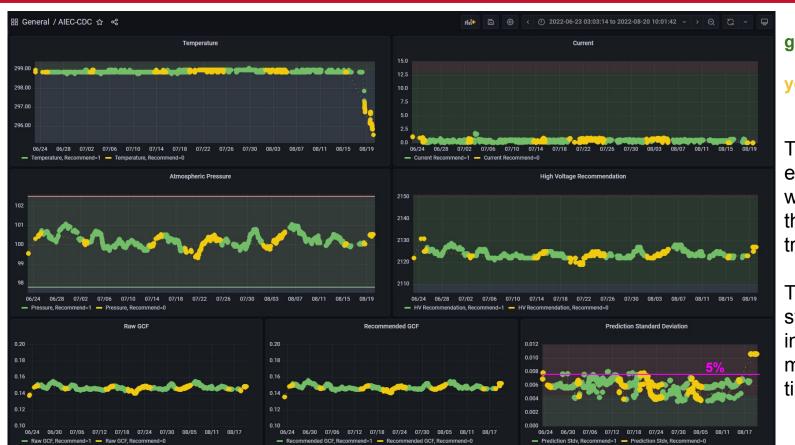


- Charged Pion Polarizability (CPP) Spring 2022
  - Used at the start of each run in the experiment



# Fully deployed system during CPP Experiment in Spring 2022





green = AI controlled

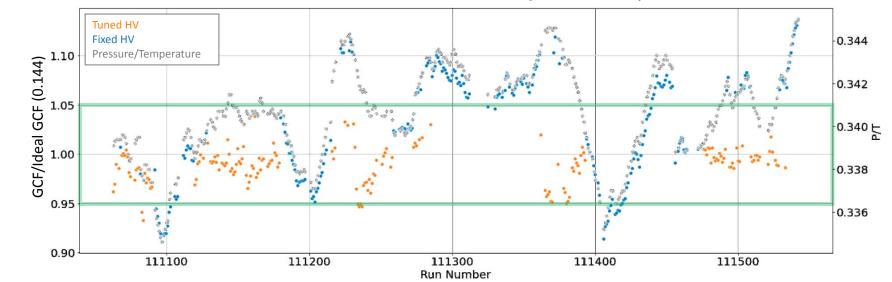
yellow = fixed HV

The CPP experiment setup was different from that for our training data set.

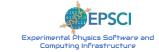
This required the system to drop into observation mode a number of times

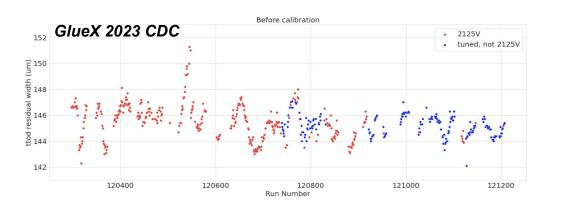
# Deployment 3 – PrimEx-η June-Dec 2022

- GCF obtained from dE/dx after the run
- Preliminary results show GCF predominantly within 5% of ideal value for runs with tuned HV
- Plot of GCF/ideal for tuned HV and fixed HV also shows pressure/temperature



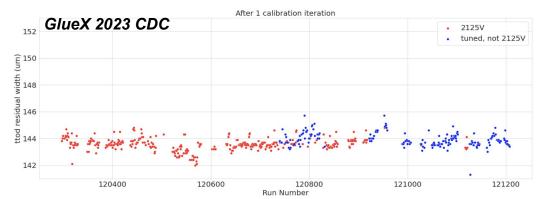
## **GlueX CDC Time to Distance Calibration**





Tuning HV to stabilize gains results in comparable or better time-to-distance resolution prior to calibrating\*.

\*addresses concern noted in the proposal



Bonus: Calibration technique for CDC Time-to-Distance developed as result of AIEC effort led to single iteration procedure. This new procedure replaced one entailing a series of 3 to 4 iterations of track reconstruction and re-fitting, and gave better and more consistent resolution.





## Part II:

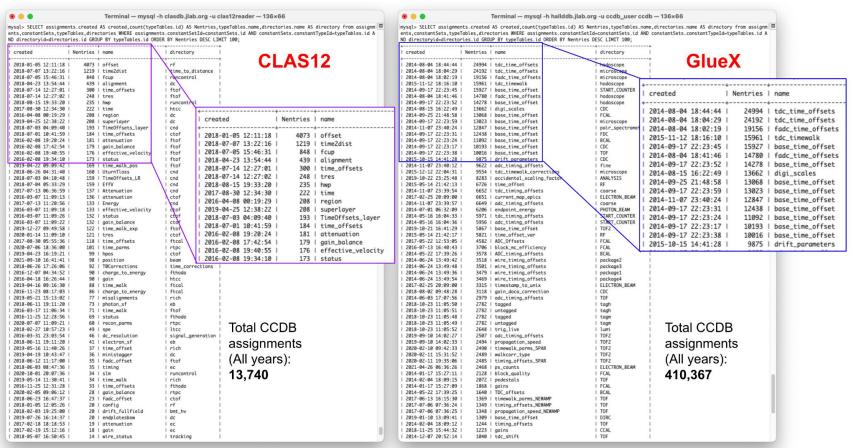
With the successful deployment of the automated AI control of the CDC, attention was turned to another detector system as outlined in the proposal.

The first candidate was the CLAS12 drift chambers.



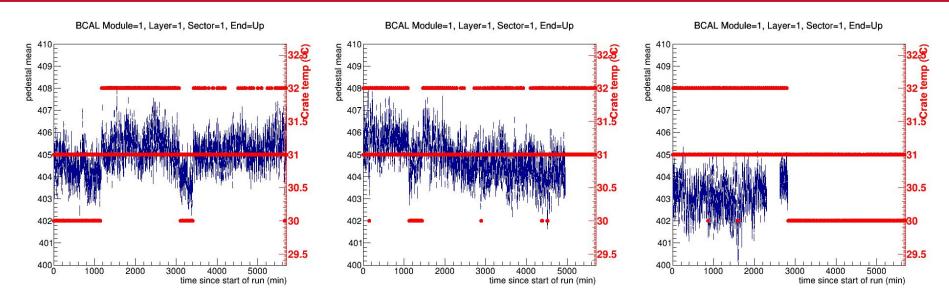
#### **Differences in Collaboration Culture?**





#### **GlueX Barrel Calorimeter Pedestals**





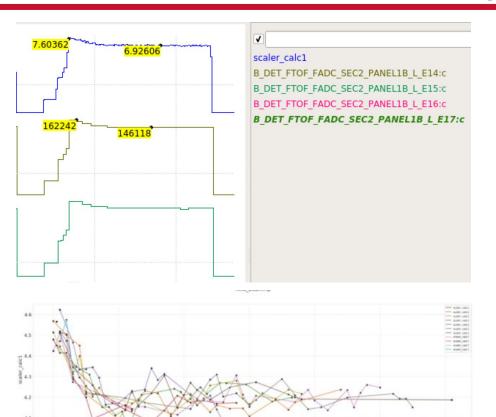
A colleague suggested to look at controlling fan speed to stabilize pedestals read by a flash ADC for a calorimeter.

Rejected due to crate temp. measurements being too coarse.



# **CLAS12 Calorimeter and TOF detector gains after beam trip**





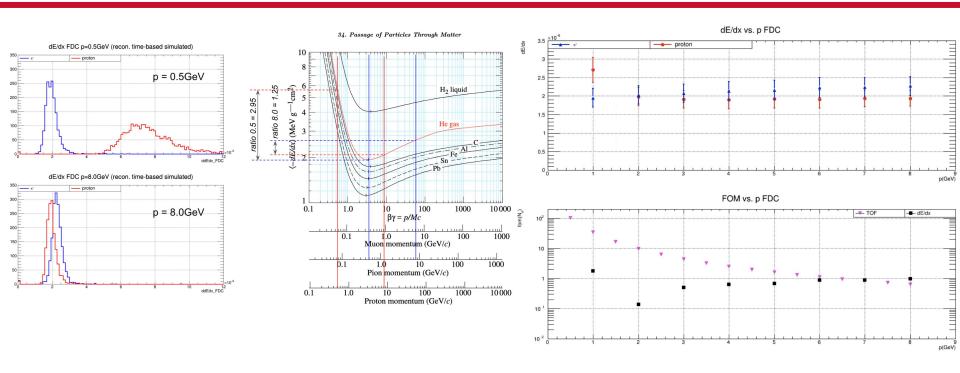
Time interval after beam trip

A colleague suggested to look at stability of gains in EM Calorimeter to just after beam trips. This could possibly benefit TOF PMTs as well.

Rejected due to observed effect being almost completely due to beam current overshoot upon recovery.

#### GlueX FDC PID from dE/dx

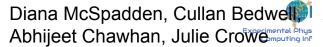




Unable to identify an approved experiment requiring good PID for particles > 5GeV



## **Calibration of the GlueX Forward Calorimeter**

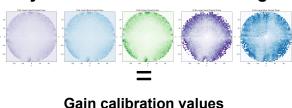


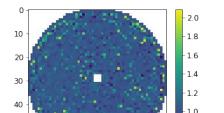


#### **Traditional Calibration:**

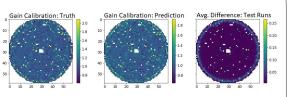
- iterative over π<sup>0</sup>s
- Requires particle reconstruction
- · Statistics sometimes difficult

# Can we use the LED monitoring system and Machine Learning?



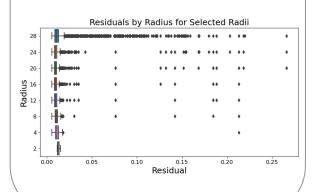






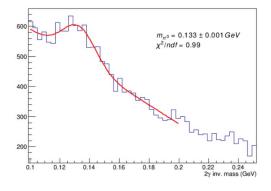
#### Average results over 5-fold cross validation

dataset	fold idx	average residual $\psi$	mape ↓	mse ↓
unmasked	average	0.258	23.848	5.183
masked	average	0.027	2.370	0.004



## **Initial Physics Comparison**

- Does prediction accuracy result in good physics results?
- We have an initial  $\pi^0$  analysis
  - Single run, entire FCAL

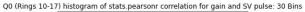


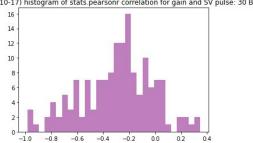
- π<sup>0</sup><sub>PDG</sub> mass: **134.98 MeV**
- Using our calibrations: 133.31 MeV



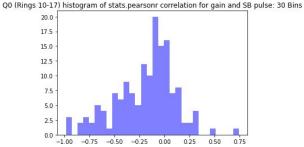
#### **Correlation Plots**



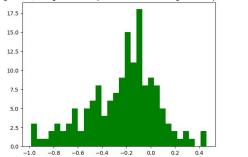




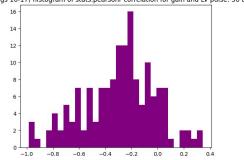




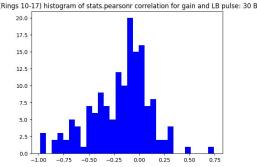




#### Q0 (Rings 10-17) histogram of stats.pearsonr correlation for gain and LV pulse: 30 Bins

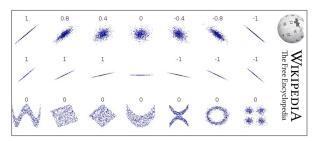


Q0 (Rings 10-17) histogram of stats.pearsonr correlation for gain and LB pulse: 30 Bins



#### Pearson correlation coefficient for LED peaks and calibration gains for different colors

#### Expect anti-correlation (values <0) but scale is smaller than expected

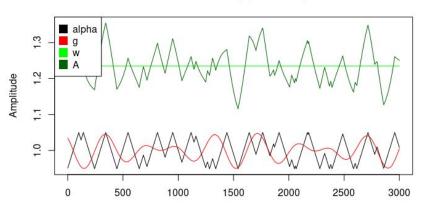




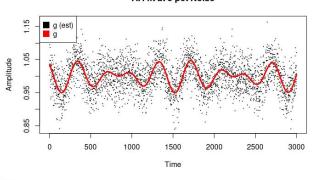
# Simulation of the LED gain monitoring system



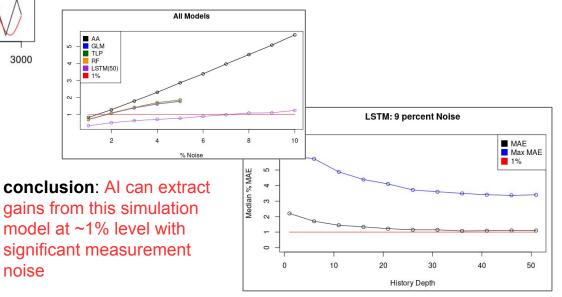
#### Gain Factors (0 pct noise)



#### AA fit at 5 pct Noise



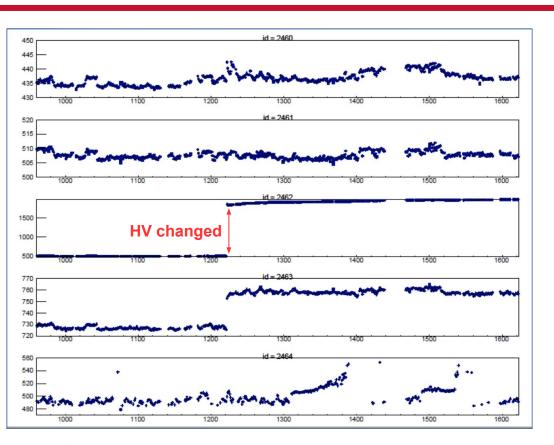
- A = ADC readout amplitude for each block and discrete time index.
- g = PMT gain for each block and discrete time index.
- $\omega$  = Optical Coupling constant for each block.
- $\alpha$  = Amplitude of LED pulsar for each discrete time index.
- R = Radiation Damage for each block and discrete time index.



noise

## Independent Analysis of LED gain monitoring system





"The clear correlation between led gain change or sometimes even jumps and  $\pi^0$  energy gain has not been seen so far, which is puzzling"

Plots are for 5 different PMTs. LED amplitude as seen by PMT normalized to LED pulser amplitude as function of time.



# **Summary**



- Reproduced calib. constants for GlueX CDC using Al model with same inputs as classic method
- Successfully *predicted* GCF calibrations using environmental data from GlueX 2018 and 2020 runs
- Successful *deployment* of Al detector control system (Gaussian Process model)
- Successful deployment of UQ aware system for CPP experiment in summer 2022
  - Now part of standard operations!
- Investigated GlueX FCAL LED monitoring system
  - UVA Capstone project for team of 4 DS students on automating Calorimeter
  - Created simulation. Extracted accurate calibrations using LSTM model
  - Unable to identify strong correlations in real data



#### **Publications**

Jeske, T., McSpadden, D., Kalra, N., Britton, T., Jarvis, N., & Lawrence, D. (2023, February). Using AI to predict calibration constants for the central drift chamber in GlueX at Jefferson Lab. In Journal of Physics: Conference Series (Vol. 2438, No. 1, p. 012132). IOP Publishing.

Jeske, T., McSpadden, D., Kalra, N., Britton, T., Jarvis, N., & Lawrence, D. (2022). Al for Experimental Controls at Jefferson Lab. Journal of Instrumentation, 17(03), C03043.

#### **Key Presentations**

#### Al Driven Experiment Calibration and Control Slides

Britton, T., Lawrence, D., Jeske, T., McSpadden, D., & Jarvis, N. (2023, May 8–12). Al Driven Experiment Calibration and Control [Conference presentation]. Conference on Computing in High Energy & Nuclear Physics, Norfolk, VA, United States. https://indico.jlab.org/event/459/contributions/11374/

#### Using Machine Learning to control the GlueX Central Drift Chamber Slides

Jarvis, N., Britton, T., Jeske, T., Lawrence, D., & McSpadden, D. (2023, January 9–13). Using Machine Learning to control the GlueX Central Drift Chamber [Conference presentation]. Conference on High Energy Physics in LHC Era, Valpara´ıso, Chile. <a href="https://indico.cern.ch/event/1158681/contributions/5192980/">https://indico.cern.ch/event/1158681/contributions/5192980/</a>

#### Control and Calibration of GlueX Central Drift Chamber Using Gaussian Process Regression Poster Paper

McSpadden, D., Jeske, T., Jarvis, N., Britton, T., Lawrence, D., & Kalra, N. (2022, December 3). Control and Calibration of GlueX Central Drift Chamber Using Gaussian Process Regression [Poster Presentation]. Machine Learning and the Physical Sciences workshop at NeurlPS, New Orleans, LA, United States. https://ml4physicalsciences.github.io/2022/

#### Gaussian process for calibration and control of GlueX Central Drift Chamber Slides

Jeske, T., Britton, T., Kalra, N., Jarvis, N., McSpadden, D. &, Lawrence, D. (2022, October 23-28). Gaussian process for calibration and control of GlueX Central Drift Chamber [Conference Presentation]. Advanced Computing and Analysis Techniques in Physics Research, Bari, Italy. https://indico.cern.ch/event/1106990/contributions/4998092/

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This work was supported by the US DOE as LAB 20-2261.

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GlueX acknowledges the support of several funding agencies and computing facilities: www.gluex.org/thanks



Backup slides



# **HV Channel Segmentation** (Prepping for Cosmics Test)





#### View from upstream

A: 3-4

B: 4-5

C: 4-5

D: 5-7

E: 5-8

F: 6-10

G: 7-11

H: 7-12

I: 8-13

A: 5-6

B: 6-7

C: 6-8

D: 8-11

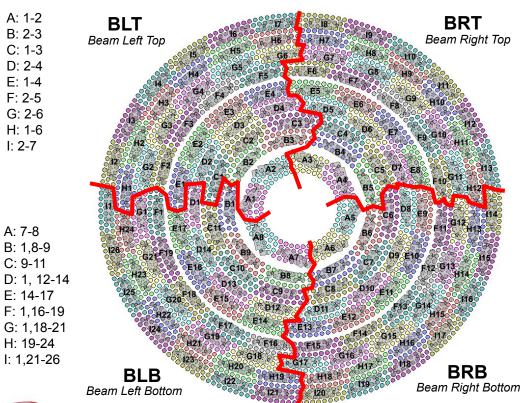
E: 9-13

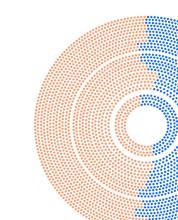
F: 11-15

G: 12-17

H: 13-18

I: 14-20





Split the CDC into 2 halves

- Leave one side at a fixed HV (conventional)
- Let the ML control the other
- Autonomously adjust HV every 5 min

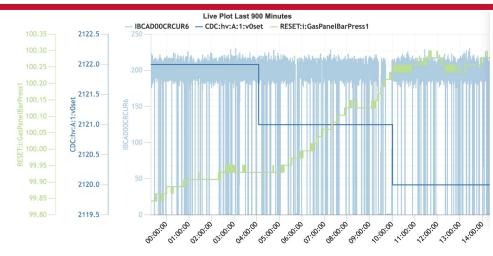
# **Observed Behavior that was Unexpected**

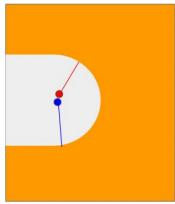


Plot to the right shows HV setting was dropping while atmospheric pressure was rising during period of constant beam current. This is the opposite of what is expected.

Issue turned out to be due to using point on surface of minimum acceptable uncertainty with the minimal Euclidean distance to actual point in feature space.

A small change in location in feature space could result in a large change in the projected location on the surface of uncertainty.





n.b. the GCF value was actually still within the few percent tolerance for operations.

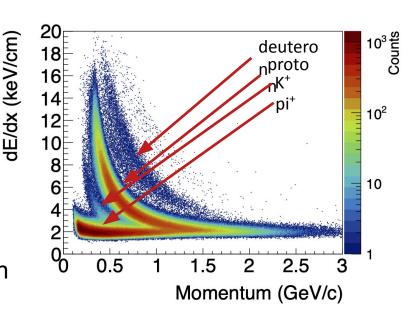


#### **CDC Calibrations**

- Gain affects PID selections in analysis
  - Sensitive to environmental conditions
    - Atmospheric pressure
    - Temperature
  - Sensitive to experimental conditions
    - Beam conditions change with the experiment

## •Traditionally:

- •GCF obtained from Landau fit to amplitude
- Calibration constants are generated per run
  - Approximately 2 hours of beam time



# **FCAL** Radiation damage



