Simulation and development of a coded source neutron imaging system

Accelerator and Detector Research and Development Program Principal Investigators' 2011 meeting

August 22, 2011 Annapolis, MD

Philip Bingham (Early Career Award), and Hector Santos-Villalobos, Oak Ridge National Laboratory





Neutron radiography

- Neutron and x-ray images complementary to one another
- X-ray attenuation increases with atomic mass
- Neutron attenuation is random with respect to atomic mass
- Resolution limited by source size for x-rays and neutrons



(Paul Scherrer Institut, http://neutra.web.psi.ch/What/index.html)



Bingham, (865)574-5680, binghampr@ornl.gov

Neutron radiography System designs

- Simple radiographic setup (source, object, detector)
 - Sources
 - Reactors, Spallation sources, Generators, and Fission sources
 - Low flux in comparison to x-ray systems
 - Large neutron facilities (10⁸ n/cm²/sec)
 - Detectors
 - Scintillator
 - Micro-Channel Plate
- Resolution driven by L, D, and object position
- Systems set high L/D and place object close to detector
- Limit in resolution by scintillator
- Magnified imaging needed for resolution
- Large source needed for SNR







Coded aperture imaging

Image formation

 $P(\mathbf{r}) = O(\mathbf{r}) * A(\mathbf{r})$

- Reconstruction
 - Algorithm

$$\hat{O}(\mathbf{r}) = P(\mathbf{r}) * G(\mathbf{r})$$
$$\hat{O}(\mathbf{r}) = O(\mathbf{r}) * (A(\mathbf{r}) * G(\mathbf{r}))$$

– Kernel

$$\hat{O}(\mathbf{r}) = O(\mathbf{r}) \quad iff \quad A(\mathbf{r}) * G(\mathbf{r}) = \delta(\mathbf{r})$$
$$G(\mathbf{r}) \equiv \begin{cases} 1 & if \quad A(\mathbf{r}) = 1\\ -1 & if \quad A(\mathbf{r}) = 0 \end{cases}$$



Pinhole

Coded Aperture



Gamma system uses linear coded aperture and CsI detector "pixels"



Coded source imaging





Coded source imaging system design

- Aperture and anti-aperture imaging
 - Reduce system noise
 - Near field effect reduction
- Magnification to improve resolution
 - Overcome scintillator restrictions
- Coded source enables higher flux
- Progress
 - Equations for resolution and field of view limitations developed
 - Coded aperture mask designs complete for various resolution levels
 - Initial tests for sputtering of Gd on Si wafer for high resolution mask manufacture are encouraging
 - Stage systems incorporated for mask and object positioning



$$O_R(\mathbf{r}) = [P^+(\mathbf{r}) - P^-(\mathbf{r})] * G^+(\mathbf{r})$$

= $[O(\mathbf{r}) * A^+(\mathbf{r}) + n(\mathbf{r}) - (O(\mathbf{r}) * A^-(\mathbf{r}) + n(\mathbf{r}))] * G^+(\mathbf{r})$
= $O_R^+(\mathbf{r}) + O_R^-(\mathbf{r})$



Coded source simulations

- Simulations performed with McStas
- Single pinhole object simulations
 - Image equals mask pattern
 - Allows validation of simulation model
- Pinhole array simulations
 - Test geometric limitations for FOV
 - Eventually used to study effects of percent open area on SNR
- Tilted edge simulations for MTF calculations







Coded source simulations Multiple pinholes

Coded source simulations MTF Calculation from Edge Response

- Coded aperture
 - MURA
 - 10µm pinholes
 - 47 x 47 base pattern
- System geometry
 - CG1D setup
 - 5.2m aperture to detector
 - 577mm aperture to object
 - Object magnification of 9
 - 40µm image plane sampling





Experimentation

- Low resolution experiments
 performed
 - HFIR CG1D Neutron imaging prototype station
 - CG1A development beam line
 - Both beam lines suffer from nonuniformities in illumination
- CG1A experiment details
 - Test setup
 - a = 50cm, b = 324-50 = 274cm, d = 1mm
 - Magnification = 6.48
 - Coded aperture
 - No two holes touching drilled holes
 - 1mm thick borated AI plate
 - R = 5pixels*0.7mm = 3.5mm
 - Hole diameter = 0.381mm
 - Object
 - Borated AI plate with 1mm diameter hole
 - Extended line objects on calibration
 wafer
 - Detector
 - Scintillator based CCD
 - Imaged pixel size = 33.95μm





Aperture

Anti-Aperture





Experimentation

- 1mm pinhole image results
 - Measured image closely resembles simulation
 - Non-uniform illumination
 - Roll off of intensity in corners
 - Reconstructed pinhole shape varies with base pattern position







11 Managed by UT-Battelle for the U.S. Department of Energy

Philip Bingham, (865)574-5680, binghampr@ornl.gov

Reconstructed pinhole size matches object and magnification

- 1mm pinhole object
- Magnification of 6.48
- Imaged pixel size = 0.034mm
- Measured diameter
 - 177 pixels
 - 177*0.034/6.48 = 0.929mm
- Resolution of system
 - CA hole size = 0.381mm
 - Resolution 0.381*(324-50)/324 = 0.322mm
- Measurement well within resolution of system







Conclusions and future efforts

- Coded source imaging simulations have shown high resolution on extended objects
- Experimentation has revealed a challenge for imaging and reconstruction in the need for normalization to handle nonuniform illumination
- Future efforts
 - Develop normalization methods for non-uniformity correction
 - Extension of simulation and reconstruction algorithms to threedimensional objects
 - Addition of x-ray radiography perpendicular to neutron beam
 - Develop mask manufacture method
- Thanks to US Department of Energy Basic Energy Sciences for project funding through their Early Career Program and support of the CG1D user facility

