Future High Performance Computing Capabilities

Summary Report of the Advanced Scientific Computing Advisory Committee (ASCAC) Subcommittee
(DRAFT VERSION — NOT FOR DISTRIBUTION)

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Chapter 1

Executive Summary

The ASCAC Subcommittee on Future High Performance Computing (HPC) Capabilities has reviewed opportunities and challenges related to the most promising technologies that are currently planned for the post-exascale (2020’s) and post-Moore (2030’s and beyond) timeframes. We briefly summarize below the key findings and recommendations from this review, from the perspective of planning and research directions that need to be given priority to prepare for the very significant challenges that await us in the post-Moore computing era. An overarching concern that emerged from the subcommittee’s deliberations is that DOE has lost considerable momentum in funding and sustaining a research pipeline in the applied math and computer science areas that should have been the seed corn for preparing for these future challenges, and it is therefore critical to correct this gap as soon as possible. While the subcommittee understands the paramount importance of DOE’s commitment to deliver exascale capabilities, we believe that it is essential for DOE ASCR to fund research and development that looks beyond the Exascale Computing Project (ECP) time horizon so as to ensure our nation’s continued leadership in HPC.

Finding 1: Need for clarity in future HPC roadmap for science applications. The challenges associated with post-exascale and post-Moore computing are receiving significant attention from multiple government agencies and initiatives including DARPA, IARPA, NSF and NSCI. The subcommittee believes that Science will need to be prepared for a period of uncertainty in future HPC technologies and computing paradigms, and that, because of this uncertainty, there is a need to focus on strategy and planning activities so as to better anticipate what the future HPC roadmap possibilities will be for science applications.

Finding 2: Extreme heterogeneity with new computing paradigms will be a common theme in future HPC technologies. As discussed in the report, there is a great diversity in the technologies that are expected in the post-exascale and post-Moore eras, which has been appropriately labeled as “extreme heterogeneity” in an upcoming ASCR workshop and related discussions. The subcommittee believes that there is value in focusing on extreme heterogeneity as a common theme in future HPC technologies, so as to enable a broader view of post-Moore computing rather than focusing solely on point solutions.

Finding 3: Need to prepare applications and system software for extreme heterogeneity. As discussed in the report, different applications have responded to past technology transitions (e.g., from vector to MPP, terascale to petascale, petascale to exascale) in different ways. We are rapidly approaching a period of significant redesign and reimplementation of applications that is expected to surpass the disruption experienced by the HPC community when transitioning from vector to MPP platforms. As a result, scientific teams will need to prepare for a phase when they are both using their old codes to obtain science results while also developing new application
frameworks based on the results of applied math and computer science research investments that need to be made now. High-quality design and implementation of these new frameworks will be crucial to the future success of DOE computational science.

**Finding 4: Need for early testbeds for future HPC technologies.** Given the wide diversity of technologies expected in the post-Moore era, accompanied by radically new computing paradigms in many cases, there is a need for building and supporting early testbeds for future HPC technologies that are broadly accessible to the DOE community, so as to enable exploration of these technologies through new implementations of science (mini-)applications.

**Finding 5: Open hardware promises to be a major trend in future platforms** With extreme heterogeneity, there is a growing trend towards building hardware with open interfaces so as to integrate components from different hardware providers. There is also a growing interest in building “open source” hardware components through recent movements such as the RISC-V foundation. For the purpose of this report, the term “open hardware” encompasses both open interfaces for proprietary components as well as open source hardware components.

**Finding 6: Synergies between HPC and mainstream computing** Though this report has focused on future high performance computing requirements from the perspective of science applications, there are notable synergies between future HPC and mainstream computing requirements. One application area where these synergies are already being leveraged, and will undoubtedly grow in the future, is in the area of data-intensive applications and data analytics (e.g., the use of neuromorphic computing and other accelerators for deep learning).

**Recommendation 1: Office of Science’s Role in Future HPC Technologies.** The findings in this study have identified the urgency of developing a strategy, roadmap and plan for high performance computing research and development in the post-exascale and post-Moore eras, so as to ensure continued advancement of Science in the future. Though there are multiple government agencies that are stakeholders in post-Moore computing, the subcommittee recommends that the DOE Office of Science play a leadership role in developing a post-Moore strategy/roadmap/plan for advancing high performance computing in the service of Science.

**Recommendation 2: Investing in Readiness of Science Applications for post-Moore era.** The findings in this study have identified the challenges involved in preparing applications for past technology disruptions, and the fact that future disruptions will require exploration of new computing paradigms as we move to extreme heterogeneity in the post-exascale and post-Moore computing eras. The subcommittee recommends that the Office of Science work with other offices of DOE to ensure that sufficient investment is made with adequate lead time to prepare science applications for the post-Moore era. While the adaptations that ECP application teams are starting to make for supporting current and emerging heterogeneous execution environments is good preparation for some of the anticipated post-exascale technologies, additional investments will be needed to explore the newer computing paradigms that will emerge in the post-exascale and post-Moore timeframes. In addition, we recommend that R&D in best practices for design and development of scientific software be given high priority to best assure that new scientific application frameworks benefit from the state of the art in software best practices.

**Recommendation 3: Investing in Research related to Open Hardware Platforms.** The findings in this study have identified the need for creating a more open hardware ecosystem in the post-exascale and post-Moore eras, relative to current and past approaches for hardware acquisition. In the interest of future Science needs, the subcommittee recommends that the Office of Science foster this ecosystem by investing in research related to open hardware platforms, i.e., platforms built using open interfaces that support high-performance and reliable integration of components from different hardware providers.
Recommendation 4: Investing in Research related to System Software. The findings in this study have identified the need for advancing system software to meet the requirements of post-Moore computing. The DOE should support active and sustained efforts to contribute to relevant software projects to ensure that HPC concerns such as performance isolation, low latency communication, and diverse wide area workflows are addressed in the design and adoption of system software for future HPC platforms.

Recommendation 5: Early Testbeds in DOE Computing Facilities. The findings in this study have identified the need for providing users of DOE computing facilities early access to testbeds and small-scale systems that are exemplars of systems expected in the post-Moore computing roadmap. The subcommittee recommends that the Office of Science’s computing facilities address this need by acquiring such testbeds and small-scale systems, and providing and supporting access to these systems by current HPC users.

Recommendation 6: Recruiting, Growing and Retaining Talent for post-Moore era. The findings in this study have identified the need for significant innovation in support of the enablement of science applications on post-Moore hardware. The subcommittee recommends that DOE national laboratories prioritize the recruiting and nurturing of top talent in all aspects of mapping applications onto emerging post-Moore hardware, including skills and talent related to development of science applications, applied mathematics research, system software research, and hardware research for future platforms.
Chapter 2

Background

2.1 Moore’s Law and Current Technology Roadmaps

Moore’s Law [2,3] has been the bedrock for growth in the capabilities of all computing systems, including high performance computing (HPC) systems. Simply stated, Moore’s Law is the prediction that the number of transistors (components) in an integrated circuit would double approximately every two years. The significance of Moore’s Law is that the semiconductor industry has strived to maintain this exponential growth for over five decades, resulting in important benefits in cost and performance for all semiconductor consumers. The cost implication of Moore’s Law is that if the cost of an integrated circuit remains approximately constant, then the cost per transistor decreases exponentially with time. The performance implication of Moore’s Law used to relate to Dennard Scaling [4], which stated that, as transistors become smaller, their power density remains constant, i.e., the power consumed by an integrated circuit remains proportional to the area of the circuit rather than the number of transistors in the circuit. An underlying assumption behind the Dennard Scaling prediction is that the power consumed by an integrated circuit is dominated by its dynamic (switching) power, which in turn is proportional to the clock frequency. As a result, when Dennard Scaling holds, the power per transistor decreases exponentially with time, which in turn made it possible to increase clock frequencies from generation to generation of a semiconductor technology without increasing the total power consumed by the integrated circuit.

One of the major challenges recently faced by the computing industry is the fact that Dennard Scaling ended over a decade ago, as shown in Figure 2.1 which includes trend data for microprocessors built during the last 40 years. (Note that the y-axis numbers are plotted on a logarithmic scale.) The first observation from the figure is that Moore’s Law has remained robust during this period, since the number of transistors in a microprocessor continued to increase at an exponential rate until the present time. However, the clock frequencies flattened in the 1 GHz (= $10^3$ MHz) range since around 2005, thereby signalling the end of Dennard Scaling. The main reason for this end is that the leakage power started becoming a significant component of the power consumed by transistors, as the transistor sizes decreased. Past 2005, any attempt to increase clock frequency became impractical because doing so would cause the chip to overheat. Instead, 2005 marked the start of the “multicore era” in which the additional transistors predicted by Moore’s Law are being used to increase the number of processor cores in a single integrated circuit, without increasing their clock frequencies.

If Moore’s Law were to continue indefinitely, we could continue getting more performance from successive generations of semiconductor technology by doubling the number of processor cores in an integrated circuit rather than by increasing the clock frequency. However, it stands to reason...
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Figure 2.1: 40 years of Microprocessor Trend Data for 1) Number of Transistors, 2) Single Thread Performance, 3) Frequency, 4) Power, 5) Number of Cores.

Table MM01 - More Moore - Logic Core Device Technology Roadmap

<table>
<thead>
<tr>
<th>YEAR OF PRODUCTION</th>
<th>2017</th>
<th>2019</th>
<th>2021</th>
<th>2024</th>
<th>2027</th>
<th>2030</th>
<th>2033</th>
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<tr>
<td>Logic Industry &quot;Node Range&quot; Labeling (nm)</td>
<td>7.00</td>
<td>5.00</td>
<td>5.00</td>
<td>3.00</td>
<td>2.10</td>
<td>1.50</td>
<td>1.00</td>
</tr>
<tr>
<td>EM-Foundry node labeling</td>
<td>FinFET</td>
<td>FinFET</td>
<td>LGAA</td>
<td>LGAA</td>
<td>VDAA</td>
<td>VDAA</td>
<td>VDAA</td>
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<tr>
<td>Logic device mainstream device</td>
<td>FinFET</td>
<td>FinFET</td>
<td>LGAA</td>
<td>LGAA</td>
<td>VDAA</td>
<td>VDAA</td>
<td>VDAA</td>
</tr>
<tr>
<td>Logic device structure options</td>
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<td>FDSOI</td>
<td>LGAA</td>
<td>LGAA</td>
<td>VDAA</td>
<td>VDAA</td>
<td>VDAA</td>
</tr>
<tr>
<td>Logic device mainstream device</td>
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<td>FDSOI</td>
<td>LGAA</td>
<td>LGAA</td>
<td>VDAA</td>
<td>VDAA</td>
<td>VDAA</td>
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<tr>
<td>Patterning technology inflection for Mx interconnect</td>
<td>193i</td>
<td>193i, EUV</td>
<td>193i, EUV</td>
<td>193i, EUV</td>
<td>193i, EUV</td>
<td>193i, EUV</td>
<td>193i, EUV</td>
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<td>Channel material technology inflection</td>
<td>Si</td>
<td>SiGe25%</td>
<td>SiGe50%</td>
<td>Ge, IIIV (TFET)</td>
<td>Ge, IIIV (TFET)</td>
<td>Ge, IIIV (TFET)</td>
<td>Ge, IIIV (TFET)</td>
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<td>Process technology inflection</td>
<td>Conformal deposition</td>
<td>Conformal Doping, Contact</td>
<td>Channel, RMG</td>
<td>CFET</td>
<td>Seq. 3D</td>
<td>Seq. 3D</td>
<td>Seq. 3D</td>
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<td>Stacking generation</td>
<td>2D</td>
<td>2D</td>
<td>2D</td>
<td>2D: P-over-N</td>
<td>3D: SRAM-on-Logic</td>
<td>3D: Logic-on-Logic, Hetero</td>
<td>3D: Logic-on-Logic, Hetero</td>
</tr>
<tr>
<td>Design-technology scaling factor for standard cell</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
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<td>1.00</td>
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<tr>
<td>Design-technology scaling factor for SRAM (1T1) bitcell</td>
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<td>Number of stacked devices in one tier</td>
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<td>Tier stacking scaling factor for SRAM</td>
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<td>18.00</td>
<td>18.00</td>
<td>18.00</td>
</tr>
<tr>
<td>FinFET footprint scaling: node-in-node: 50% digital, 35% SRAM, 15% area/HD</td>
<td>-</td>
<td>64.9%</td>
<td>51.3%</td>
<td>64.3%</td>
<td>64.2%</td>
<td>80.3%</td>
<td>96.7%</td>
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</tbody>
</table>

Table 2.1: Projections for the continuation, and end, of Moore’s Law during the next 15 years (Source: IEEE IRDS 2017 Edition).
that Moore’s Law must come to an end due to basic physical limitations, including the fact that the size of the atoms used in silicon chip fabrication is around 0.2nm. Table 2.1 shows the projected transistor size (“node range”) decreasing from 10nm in 2017 to 1.0nm in 2033, at which point a single transistor would shrink to the size of five Silicon atoms. Further, achieving the reductions shown in Table 2.1 will require major technology advances, including monolithic 3D transistors expected from 2024 onwards. It is therefore clear that alternate computing technologies and paradigms urgently need to be explored for future HPC, to ensure the continued and sustained performance gains to which HPC users and customers are accustomed. Given this context, we will refer to the 2020’s decade as “post-exascale” and the 2030’s decade and beyond as “post-Moore” in this report.

2.2 Levels of Disruption in Post-Moore era

The IEEE Rebooting Computing Initiative [1] has characterized a range of possible approaches to address the end of Moore’s law. As shown in Figure 2.2, these approaches can be classified in terms of the amount of disruption to the computing stack they would require [1].

The least disruptive approach in Figure 2.2 is for the industry to find a drop-in replacement for the CMOS switch. Existing transistor technologies cannot be both power efficient and operate reliably at the scales at the end of the roadmap. Thus, this approach is to create a new transistor technology. Although this is the least disruptive approach to the computing stack, it is exceedingly challenging. The IRDS roadmap shows that Moore’s Law will run out even with these new transistor types by 2033 [5].
The next least disruptive approach is to use novel ways to construct computer microarchitectures while still maintaining software compatibility to the existing software base. These include microarchitectures implemented using techniques such as some Silicon Photonics approaches (Section 4.3). Other approaches not discussed in this report include adiabatic/reversible logic and cryogenic/superconducting logic.

The next disruptive approach involves making architectural changes that are “programmer visible.” Where these approaches will require new programming systems, they generally do not abandon the von Neumann computing paradigm. These approaches include Reconfigurable Logic (Section 4.1), Memory-Centric Processing (Section 4.2), and some approaches that employ Silicon Photonics (Section 4.3), all of which are promising approaches for the post-exascale era.

The most radical (Level 4) approaches rethink computing paradigms from the ground up, and will require new algorithms, programming systems, system software, and hardware. Examples of this include Neuromorphic Computing (Section 4.4), Quantum Computing (see Section 4.5) and Analog/Thermodynamic Computing (Section 4.6). All of these represent potential candidates for the post-Moore era.

2.3 National Landscape for Post-Moore Computing

Leadership in HPC is critical to the success of many Federal agencies, as well as that of many commercial enterprises; all these players are concerned about what the future portends beyond the end of Moore’s Law. Many are investing, or planning to do so, and there is an opportunity for DOE to coordinate its efforts with them, so as to maximize the benefit to all. Where serious sustained investments are being made, DOE need not duplicate them. For example, DARPA is investing in both specialized analog quantum systems (QEO) and the foundations of general purpose devices (LOGIQ). DARPA is also exploring superconducting logic as the basis for classical computing (C3). DARPA MTO is developing a new research initiative targeting an electronics resurgence, and at this early stage, DOE can perhaps influence directions that can have synergistic benefits with science applications. MTO is already investing in HPC related technologies such as hybrid analog and digital systems (ACCESS), design automation (CRAFT), IP reuse (CHIPS), integrated photonics (POEM), and energy efficiency (PERFECT). And, of course, many commercial enterprises are investing in the development of special-purpose accelerators for deep learning and related AI algorithms and applications.

A key point underlying all the activities under way in other agencies and commercial entities is that, while they may not be directly working on advancing HPC for science applications, they are investing in technologies that could be highly relevant to DOE’s future HPC roadmap for science. It is also worth noting that the NSCI has designated DOE as playing the leadership role for HPC. Therefore, DOE has a unique opportunity to not only explore the future of HPC for scientific leadership, but to also determine if the broader HPC technology investments in the US government are adequate to enhance and sustain the economy and security of the US as has been done by past investments in computing technologies.

2.4 International Landscape for Post-Moore Computing

In late 2013, IEEE launched the international IEEE Rebooting Computing Initiative (IEEE RCI) to begin to look at potential post-Moore computing possibilities [1]. Since that time, IEEE RCI has held four invitational summits of thought leaders across multiple fields. The IEEE RCI sponsors the International Conference on Rebooting Computing (ICRC), now in its second year (2016 was its
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inaugural year). ICRC attracts researchers from around the globe to share their best post-Moore computing ideas.

In 2016, the Semiconductor Industry Association pulled its sponsorship for the venerable International Technology Roadmap for Semiconductors (ITRS). IEEE moved swiftly to become the new sponsor of the roadmap. To give the roadmap a post-Moore viewpoint, two new focus teams were added, one to track application performance and one to track architectural ideas. The IEEE renamed the roadmap the International Roadmap for Devices and Systems (IRDS) in part to avoid copyright concerns, but moreover to stress the changing nature of the industry towards post-Moore technology considerations [1]. IRDS partner organizations include the Japan Physics Society’s Systems and Devices Roadmap for Japan (SDRJ) and the EU’s NanoElectronics Roadmap for Europe: Identification and Dissemination (NEREID). IRDS produced a roadmap at the end of 2017 and will continue the ITRS’ historic cadence of a new roadmap every two years, with a roadmap update in the intervening years [5].

Finally, subcommittee members are aware of recent announcements from China, Europe and Japan related to Quantum Computing and Neuromorphic Computing that foretell a high level of international competitiveness in the post-Moore Computing era.

2.5 Interpretation of Charge

The subcommittee appreciated the timeliness of the charge, a copy of which is included in Appendix A. At the same time, we acknowledge that a single study cannot provide a comprehensive answer to identifying research opportunities and challenges for future HPC capabilities in the post-exascale and post-Moore timeframes, which span multiple decades. We trust that there will be follow-on studies to elaborate further on these challenges and opportunities as details of emerging HPC technologies become clearer in the coming years. To focus our efforts in this study, we made the following two assumptions when interpreting the charge:

- There are multiple Federal government initiatives and programs in the early stages of addressing the challenges of post-Moore computing. The subcommittee explicitly restricted the scope of this study to considerations pertinent to the use of computing for the advancement of Science, thereby focusing on the Office of Science’s mission needs, while still identifying synergies with strategic needs of other government agencies and commercial endeavors.

- The charge did not specify a timeframe to be assumed for our recommendations, though it was clear that the charge refers to timeframes that follow the accomplishment of exascale capability in the DOE. The subcommittee concluded that it was appropriate to focus on different timeframes for different technologies, based on their anticipated levels of readiness. These timeframes include the post-exascale (2020s) and post-Moore (2030s and beyond) eras mentioned earlier.
Chapter 3

Application lessons learned from past HPC Technology Transitions

3.1 Background

All HPC technology transitions have been focused on algorithm and application designs that expose more concurrency and locality. The advent of vector supercomputers such as the Control Data Cyber 205 and Cray 1 were notable early examples. Application developers organized data and computations to expose unit stride memory accesses and conflict-free writes that could be written as Q8 function calls on the Cyber 205, or converted to Cray vector instructions by the compiler. Clock speed improvements and improved functional parallelism (simultaneous execution of instruction streams) were very important for performance improvements from one generation of machines to another, and had the advantage of not forcing substantial application refactoring to realize those benefits.

Disruptive transitions occurred when the fundamental strategy for organizing data and computations changed. Vector supercomputing applications represented the first large body of optimized applications where the data and computation strategies were specialized to match a particular parallel computing model. Multiprocessing vector computations were also important, but few codes were explicitly organized to exploit multiple vector processors, relying instead on shared memory fork-join models that required minimal code modifications. The first Gordon Bell Prize was given for a auto-tasked, vectorized version of a multifrontal, super-nodal sparse direct solution on an 8-processor Cray Y-MP, but, practically speaking, the best use of multiple Cray vector processors was to improve job throughput of single processor vector codes.

3.2 Vector-MPP Transition

The large body of vector HPC applications developed in the 1980s and early 1990s represented a valuable collection of HPC capabilities. While IBM mainframes had caches and CDC memory-to-memory vector computers enabled optimization-focused coding, Cray systems were available long enough to allow the HPC community an opportunity to create a large number of highly optimized codes for defense, engineering, weather, chemistry, oil & gas applications, and more. Many of these codes were large and full-featured. The arrival of Massively Parallel Processing (MPP) computers, which relied on a very different data and computation organization, represented a challenge to developers of vector applications. There was no incremental transition path from a shared memory vector design to a distributed memory MPP design.
Many vector codes did not make the transition to MPP. For those that did, the most successful transitions started by first designing a new application framework specifically for distributed memory. Typically the framework partitioned logically global objects such as grids for PDE calculations into distributed subgrids with halos, and then provided halo exchange functions that would update halo values when called. The framework also provided reduction operations such as distributed dot products.

Given such frameworks, most of the computations that were part of the vector code could be migrated into the new with minimal changes. Assuming the halo exchange operation had been called to exchange remote values, halos enabled most computations to work with local data, just as before. Local reductions now needed a single new step to compute the global reduction. It is also worth noting that vectorization was not important for early MPPs. Maintaining vectorizable code is difficult because its presence is ubiquitous and often requires special design considerations. Without regular testing, vectorization impediments were introduced as new features are added to the code. In most MPP codes, vectorization features were not maintained, and eventually removed, especially as cached data access became more important.

The transition from vector computing to MPP was very challenging because constructing the new MPP framework took substantial time (months or years), during which the previous vector code had to remain the production platform, and the development team was split across two codes. Many vector codes were eventually retired as new MPP code emerged.

### 3.3 Terascale-Petascale Transition

The Terascale to Petascale transition has been less disruptive overall. For most applications this transition was incremental in the sense that the MPP framework remained valid. Certainly, the framework had to be refined and scalability bottlenecks removed, as the number of distributed processors and the partitioning of data increased. But there was no disruptive ramp-up phase as was the case in the vector to MPP transition.

The path to Petascale included the introduction of small scale threading (e.g., using OpenMP threading with a modest number of cores), use of GPU accelerators, and exposing vectorizable code to compilers. But these features did not force a complete redesign for most codes. Instead, application developers had to incrementally refactor the most important computational kernels to run well and could leave much of less intensive code untouched. One notable exception was the disruptions incurred for migrating applications to the petascale RoadRunner computer, which were more extensive than for other (later) petascale systems. However, it can also be argued that the application changes needed for the RoadRunner system may have served as good preparation for the multi-GPU on-node parallelism (as an example) that needs to be exploited on exascale systems.

The approach used for terascale to petascale continues to be very effective, even as we go beyond petascale. In fact, it is the primary strategy used to port applications to the current fastest LINPACK machine, the Sunway TaihuLight. This system has thousands of distributed memory nodes that can be used as a large Linux cluster by mapping execution to just the Management Processing Elements (MPEs). Porting any MPP code to the MPE processors of the TaihuLight platform is very straightforward if the code is designed to run on scalable Linux clusters. Performance of the initial port is very poor, since the MPEs represent a tiny fraction of the system performance. But once the code is working on the MPEs, incremental porting of functionality to the CPEs (8x8 processor mesh) is possible, and is very similar to porting strategies use for GPU offloading. Certainly, very substantial data structure and execution strategy changes are required, but again an incremental approach is possible.
3.4 Petascale-Exascale Transition

The petascale to exascale transition is currently under way. So far, the terascale to petascale approach is working well as a starting point for the petascale to exascale transition. At the same time, the applications that have been successful using this approach are typically highly structured and compute-intensive, but have still not achieved uniformly high performance across all the problem formulations that they are designed to handle. Furthermore, they are not prepared for simultaneous heterogeneous execution, where subproblem sizes must vary to tune for optimal performance on different processor types, nor is there sufficient on-node control of data partitioning and mapping, or concurrent execution of heterogeneous tasks. The DOE Trinity platform, with an equal number of Haswell and Knights Landing nodes requires exactly this kind of flexibility in order to simultaneously use both halves of the system.

In order to bring a full portfolio of applications to the exascale threshold, and to bring all applications forward beyond exascale, we face another disruptive phase. The growth of on-node concurrency, the need to execute concurrently on multiple heterogeneous nodes, and the increasing penalty for having any sequential execution regions in our codes mean we are on the front end of a new transition. While there is much research required, early indications are that we need to introduce new control layers and system software support (e.g., to support asynchronous tasking), that will enable us to better handle simultaneous heterogeneous execution, support task-enabled functional parallelism and latency hiding, and move toward an effective strategy for implementing application-level resilience capabilities.

3.5 Lessons Learned

A summary of some of the key lessons learned from the three transitions summarized above is as follows:

- Vector-MPP: Investing in new application frameworks, built using results from related Applied Math and Computer Science research, was critical for success in this transition.

- Terascale-Petascale: Leveraging incremental approaches to application migration can be extremely valuable, when possible to do so.

- Petascale-Exascale: Investing in new control layers and system software support (e.g., for asynchronous heterogeneous tasking and data movement) is helpful for addressing the disruption of large on-node heterogenous parallelism.

The HPC community has been gaining experience with increasingly diverse computing architectures. Heterogeneous architectures, first broadly encountered with attached GPUs (e.g., Titan), and now present on the TaihuLight and Trinity platforms have exposed application developers to the demands that we must address. In particular, our application designs and base implementations must lend themselves to rapid adaptation to new node architectures and flexible execution models. Use of discrete devices has also taught us important lessons of shipping computation to data and managing remote resources.

In addition, code teams are migrating to new languages as opportunities arise. For example, several Exascale Computing Project codes that were formerly Fortran or C based, e.g., NWChemEx and SLATE, have moved to C++. Teams report that C++ enables more rapid code development and improved adaptability, and many programming model research projects now offer C++ library interfaces as a primary parallel programming interface for scientific application developers.
Even so, we have much to learn about software design. Porting existing codes to new platforms can require a monumental effort, or can be designed into the code. An example of the former is the recent Gordon Bell finalist paper on porting the DOE climate CAM-SE dynamical core code to TaihuLight [6]. The authors reported that the effort required modification of 152,336 of the original 754,129 lines of code (20%), and the addition of 57,709 new lines (8% increase). While this porting effort was incremental, it is still very expensive. In contrast, the Uintah application [7] is coded using C++ with template meta-programming techniques that enable compile time mixing of platform-specific adaptations to general parallel pattern expressions. This approach enables support of many node types from the same source, including simultaneous heterogenous execution on more than one type.

3.6 Assessing Application Readiness

The lessons learned from past technology transitions confirm that mapping applications to new platforms can be costly and risky. Most computational scientists are focused primarily on the new scientific insights that can be achieved through computation. Combined with the competition to produce new scientific results on a regular cadence, few computational scientists are prepared to take on the risk of migrating applications to new computing paradigms, unless absolutely necessary.

We briefly present an exemplar scorecard framework that can be used to assess application readiness for new computing platforms and paradigms. Table 3.1 lists attributes can be used to assess and prioritize scientific problems that would be good early targets for future HPC systems. A high rating in all areas indicates strong likelihood of success as an early adopter. The goal of this kind of analysis is to identify a first list of priority research directions for each target computing approach. The contents of the table include a simple illustration using sparse linear solvers as a target problem.

3.7 Next Steps

We believe that recent experiences with preparing applications for emerging heterogeneity will also help with preparations for some of the post-exascale technologies in Chapter 4 though new challenges remain for post-Moore technologies. A good resource for any software refactoring effort is the book entitled “Working Effectively with Legacy Code” by Michael Feathers [8]. This book provides a practical step-by-step approach to planning and executing changes in an existing code for any purpose. Fundamental to the effort is covering the code that will be refactored with adequate regression testing. The scope of change should be incremental when possible, making sure that one change set is fully integrated and tested before starting the next.

Of course, the disruptive transition required to introduce a tasking control layer and supporting system software between the current MPI and low-level threading and vectorization layers cannot be easily partitioned for incremental changes. Even so, Feathers’ basic strategy can guide part of the approach. In addition to Feathers’ strategies, we need to use the same basic approach that succeeded when moving from vector to MPP codes. We need to first construct a new framework that includes only a minimal representative subset of the application’s functionality. Then we construct the new framework to include the MPI (SPMD) and threading/vectorization layers of the old application, and a new task control layer in between the two. Proper design and implementation of these new frameworks is essential, and will impact scientific developer productivity and software sustainability. Adequate investment in R&D of best practices for scientific software is essential, and should be on an equal footing with R&D in other Office of Science research areas.
### Future High Performance Computing Capabilities

<table>
<thead>
<tr>
<th>Problem: Large sparse linear systems on von Neumann (vN) + accelerators/interconnect/memory-centric. (Non von-Neumann notes)</th>
<th>Score</th>
</tr>
</thead>
<tbody>
<tr>
<td>Potential Opportunities for R&amp;D are numerous for all vN+accel, interconnect and memory centric. (Non-vN options are possible, but appear to have lower potential.)</td>
<td>High</td>
</tr>
<tr>
<td>Readiness Current algorithms, with adaptations that are underway already, are suitable for vN, interconnect and memory centric. (Fundamentally new approaches are needed for non-vN.)</td>
<td>High</td>
</tr>
<tr>
<td>Novelty Many known approaches that can be explored first. (There are potential algorithms for non-vN architectures. Solution of real valued systems can be recast in the complex field for use with at least one known quantum algorithm. ML-based approaches could be a suitable replacement for a linear solver, at least to a coarse level approximation.)</td>
<td>Medium</td>
</tr>
<tr>
<td>Demand Linear solvers remain an important enabling capability for many scientific problems. On vN, interconnect and memory centric, funding for new algorithms (which will typically be incremental) is important.</td>
<td>High</td>
</tr>
<tr>
<td>Feasible Adaptations to all vN technologies are feasible with adequate resourcing.</td>
<td>High</td>
</tr>
<tr>
<td>Total Rating Overall possibility that this is a high priority research direction.</td>
<td>High</td>
</tr>
</tbody>
</table>

Table 3.1: This table shows a simple illustration using sparse linear solvers as the target problem. For all von Neumann technologies, this is a good target problem. For non-von Neumann architectures, linear solvers do not have a clear mapping. In fact, alternative algorithms are most likely required, or the need to solve a linear system may be bypassed completely.

Despite some promise from initial efforts to introduce tasking, there are many research questions that must be addressed. Examples include what new mathematical formulations expose better computation intensity, how we can realize the potential of asynchronous execution in the presence of deep memory hierarchies that further penalize remote data accesses, how to effectively schedule fine grain dynamic work loads and how to write software that is easily adapted to a variety of heterogeneous processors. Furthermore, the disruptive change that this effort requires (similar to the vector-to-MPP transition in the 1990s) will be experienced across the entire DOE application portfolio. Over time, asynchronous tasking (for computation and data movement tasks) may become a replacement for message passing. A task-based model can provide a more expressive and flexible environment for parallel execution, especially for applications that have rapidly changing dynamic workloads.
Chapter 4

Future HPC Technologies: Opportunities and Challenges

In this chapter, we provide a summary of six major technologies (Chapters 4.1–4.6) that the subcommittee felt were most representative of the trends expected in future HPC systems, based on our current knowledge. While there are some natural omissions in this list (e.g., application-specific computers like Anton 2 [9], or computing with carbon nanotube transistors [10]), our belief is that the general findings and recommendations that were derived from studying these six technologies will apply to other future HPC technologies as well.

4.1 Reconfigurable Logic

Application-specific acceleration hardware mapped onto Field Programmable Gate Arrays (FPGAs) offers a low-power, high performance option for exascale and post-exascale computing. Though the primary use of these devices was general purpose glue logic between ASICs, reconfigurable computing with FPGAs has been pursued for almost three decades [11], [12]. Over this period of time, FPGA architectures have evolved to complex systems on chip, including embedded processors, on-chip reconfigurable memory, network interfaces, DSP arithmetic blocks, and millions of system gates to hold arbitrary application-specific logic. For some application kernels, FPGAs can offer two orders of magnitude performance improvement over general purpose processors.

Research into reconfigurable computing was supported by the DARPA Adaptive Computing Systems program, which led to the design of coarse grained reconfigurable architectures such as PipeRench [13] from CMU, RAW [14] from MIT, and MorphoSys [15] from UC Irvine. Coarse grained architectures have primarily 8-16 bit data paths and function units in contrast to fine grained FPGAs with bit level resources. RAW was commercialized as the Tilera chip. Other commercial coarse grained reconfigurable architectures that have come and gone included MathStar [16] and Ambric [17]. The Tensor Processing Unit [18] from Google is a recent example of a coarse grained reconfigurable architecture specialized for neural network processing. While general purpose coarse grained architectures have not been stable in the marketplace, FPGAs remain highly successful commercial offerings with architectures suitable for a wide range of applications, including, for some large FPGAs, high performance computing.

Despite successful demonstration of many applications on FPGAs, interest in reconfigurable computing for HPC declined in the last decade with the advent of GPGPUs, which were capable of many factors of performance improvement over CPU at a fraction of the cost of high end FPGAs, and considerably easier application development cycle [19]. Recently however, the drivers of im-
Figure 4.1: Growing an ecosystem for Amazon EC2 F1 FPGA instances (image source: https://aws.amazon.com/ec2/instance-types/f1)

proved performance per watt and better memory bandwidth utilization has resulted in a renewed interest in reconfigurable computing elements in exascale and post-exascale architectures.

Applications exploiting FPGAs were initially in bioinformatics (sequence alignment such as Smith Waterman or Needleman-Wunsch), signal processing, image processing, and network packet processing [20]. Of these, signal and image processing continue, especially in deployed platforms, and network packet processing has grown. The latter has been adopted in the finance sector [21] to enable microsecond turnaround by processing the packet payload on the network interface without having to make a round trip through the CPU. Database acceleration, data analytics for search engine applications and genomics have also been pursued, often in the context of an appliance.

In scientific computing, recent algorithmic studies investigating the impact of reduced precision arithmetic on numerical stability are particularly relevant to reconfigurable logic that can support custom floating point formats [22].

The slow adoption of FPGAs for general purpose application acceleration has been principally due to the difficulty of mapping algorithms to hardware. For maximum performance, key kernels are written in Hardware Description Language (HDL), which requires hardware design expertise and has a much longer development cycle than software. High Level Synthesis (HLS) of C, C++, or OpenCL [23] continues to improve in quality of generated hardware and synthesizable subset of the language. However, performance gain is more comparable to GPU when HLS is employed. Additionally, the compile cycle (synthesis, map, place, and route) can take hours to days for large FPGAs and complex designs.

Factors that improve the prospects for reconfigurable computing with FPGAs in the exascale to post-exascale timeframe include

- increased urgency to reduce power while concurrently increasing compute capability
• improvements in design tools and access to design tools through the Amazon "free" design tool model (see below)
• increases in availability of open source hardware Intellectual Property (IP) libraries
• cloud-based application kernels and libraries from third party sources
• integration of data analysis with simulation
• workflows that can exploit in-transit data processing

Technology Readiness Timeframe: FPGAs are available today and with the Intel acquisition of Altera, it is feasible to have close integration of CPU with reconfigurable logic in 2-5 years. Early adoption in the data analysis and in-transit processing areas are most promising: for example, using reconfigurable logic to compress, clean, filter data streams generated by instruments [24].

Recently, FPGAs have become available in cloud computing servers, as illustrated by Amazon’s F1 FPGA option for compute nodes (Figure 4.1). In the Amazon business model, application developers can create FPGA applications for the F1 in the Amazon cloud. Developers can offer those applications for customers to use. Customers pay for each use of the F1 configured to run the application in the same way they pay for any other cloud resource. This model enables more people to create FPGA applications since the cost of the CAD tools, FPGA board, and associated software are provided by Amazon. This model may ease the considerable burden of developing the reconfigurable computing hardware blocks for many commercial use cases, and may eventually lead to creation of an ecosystem that would support HPC needs.

4.2 Memory-Centric Processing

Memory-centric processing is a technique that places processing closer to memory than a conventional core. This typically means that the logic is outside the normal cache hierarchy, including typically outside the coherency mechanism for multi core. As shown in Figure 4.2, there is a definite taxonomy for memory-centric processing, which includes:

• In Cell: within the bit cell storing the data.
• At the Sense Amps: at the bottom of the block of memory cells, at the first point where the data is converted to a digital level, and where it has access to literally hundreds to thousands of bits from a complete “row”
• In-Situ: a bit further down the digital chain but still within a memory bank, typically just after a “column” multiplexer that is driven from the output of the sense amps.
• On Memory: on the memory die itself, typically with access to all the independent memory banks on the die.
• In Memory: On a die between a memory, or stack of memory die, and the processor.
• Near memory: near the memory controller that may be on the memory die, but typically on a processor die.

Table 4.1 illustrates several performance characteristics for these different levels of memory-centric processing. The columns are as follows:
## Future High Performance Computing Capabilities

<table>
<thead>
<tr>
<th></th>
<th>Bits Reachable</th>
<th>Bits per Access</th>
<th>Accesses per Sec (M/s)</th>
<th>Bandwidth (GB/s)</th>
<th>Movement on Chip</th>
<th>Functionality</th>
<th>ECC Possible</th>
</tr>
</thead>
<tbody>
<tr>
<td>In-Cell</td>
<td>1</td>
<td>1</td>
<td>50</td>
<td>0.006</td>
<td>0</td>
<td>Bit-level SIMD</td>
<td>No</td>
</tr>
<tr>
<td>At Sense Amps</td>
<td>1Mb</td>
<td>2Kb</td>
<td>50</td>
<td>12+</td>
<td>Down Column</td>
<td>SIMD + Full core (Up to Vector)</td>
<td>Yes</td>
</tr>
<tr>
<td>In-Situ</td>
<td>1Gb</td>
<td>2Kb</td>
<td>50</td>
<td>12+</td>
<td>Down Column</td>
<td>SIMD + Full core (Up to Vector)</td>
<td>Yes</td>
</tr>
<tr>
<td>On-Memory</td>
<td>8Gb</td>
<td>64b</td>
<td>400</td>
<td>3.2</td>
<td>Down Bank</td>
<td>SIMD + Full core (Up to Vector)</td>
<td>Yes</td>
</tr>
<tr>
<td>In-Memory</td>
<td>4-8GB</td>
<td>1Kb</td>
<td>800</td>
<td>100</td>
<td>Across Chip</td>
<td>Full Core</td>
<td>Yes</td>
</tr>
<tr>
<td>Near-Memory</td>
<td>64+GB</td>
<td>64B</td>
<td>400</td>
<td>3.2</td>
<td>Across Chip</td>
<td>Full Core</td>
<td>Yes</td>
</tr>
</tbody>
</table>

Table 4.1: Performance characteristics for different levels of memory-centric processing.

- **Bits Reachable**: the number of different bits that might be accessible by a core at the specified location generating an address. For example, for “In-Situ” a core would have access to all the data in the memory block, whereas for “On Memory” it may have access to any of the memory on the die.

- **Bits per Access**: On each access, how many bits are possibly returned to the core. For example, for “In-Situ” it may be the width of a memory bank row.

- **Accesses per Sec (M/s)**: From a core in the specified position, how many different memory accesses could be made per second. For example, a 3200 MT/s DDR4 DIMM with a burst depth of 8 can make up to 400M accesses/s.

- **Bandwidth**: The product of the above terms, bits per access and access rate.

- **Movement on Chip**: How far across a die must data be moved to get to either the processing core or the off-chip interface that leads to the core. This is a significant energy event.

- **Chip Crossings per Access**: How many times must a chip edge be crossed. This is a very significant energy event.

- **Functionality**: What kind of processing is reasonable.

- **ECC Possible?**: Is it feasible to include ECC - both the extra bits and the logic.

The rationale for doing this comes from the increasing need to speed up problems where memory bandwidth dominate, and where there is a lot of memory against which perhaps specialized operations are to be performed. The benefits include reduced latency, reduced energy of transport, ability to make atomic operations go faster, and high levels of concurrency in systems with lots of memory and memory channels. Architecturally, the key issues are how to maintain some level of coherency with copies of the same data further down the cache hierarchy, how to spawn such
remote computations, how to maintain a global address space, how to recognize completion of such operations, and how to handle cases where data from several separated memories need to be combined.

**Technology Readiness Timeframe:** Looking forward, while examples exist of all these techniques today, the latter (Near Memory) is perhaps of most interest in the applicability to 3D stacks, where the bottom of the stack has logic and network routing, and this is at worst a few years away there is no technological challenge. Also DARPA’s “chiplet” program may very well develop processors that can be combined with a variety of memory technologies, as will possibly SRC’s recently awarded JUMP programs. Candidates for “killer apps” include memory-centric streaming operations such as encryption/decryption, search, big data, big graphs, and possibly deep learning.

### 4.3 Silicon Photonics

Among the technologies emerging toward creating a fundamentally energy efficient interconnect, photonics is perhaps the most promising to enable a transition to a new generation of scaled extreme performance computing systems [25]. Optical technologies can directly impact the critical commu-
communications challenges within computing systems through their remarkable capabilities to generate, transmit, and receive ultra-high bandwidth densities with fundamentally superior power efficiencies and with inherent immunity to noise and degradation. Unlike prior generations of photonic technologies, recent breakthroughs in silicon photonics offer the possibility of creating highly-integrated platforms with dimensions and fabrication processes compatible with electronic logic and memory devices. During the past decade, a series of major breakthroughs in silicon photonic devices has demonstrated that all the components that are necessary to build chip-scale photonic interconnect components (e.g., modulators, filters, switches, detectors) can be fabricated using common CMOS processes.

4.3.1 Current Photonic Interconnect Technologies

Most optical links in today’s supercomputers are based on multi-mode optical fibers and Vertical Cavity Surface Emitting Lasers (VCSELs). They are also generally built around a one channel per fiber format. Signals received from the electrical side are directly used to drive the laser diode, without format conversion or adaptation of any kind. Based on recommendations issued by standardization bodies such as IEEE, transceivers receive electrical signals at 10, 14, 28 Gb/s on one to ten lanes, each being coupled into its separate fiber. Transceivers with electrical signals at 56 Gb/s (QSFP56 format) will arrive soon in the market. Standards for electrical signaling at 112 Gb/s are in preparation. Traditional non-return-to- zero (NRZ) signaling will be kept for 56G but most likely PAM4 signaling will be adopted for higher speeds. Directly modulated VCSELs have been shown capable of supporting extreme bitrates provided that the adequate driving circuitry realizing pre-emphasis is provisioned alongside [26]. The power consumption of these circuits, however, may become discouraging. Products with 50 Gb/s or more per lane are only about to emerge, but VCSEL based systems have been scaled beyond the 50 Gb/s already, by means of fiber parallel systems. Multi fiber array connectors (MPO) with up to 24 fibers have been standardized (TIA 604-5-D) and standards with 72 fibers are in preparation. Such fiber ribbons and multi fiber connectors are, for instance, used in commercial products as Cisco’s CPAK 100GBASE-SR10 module. The CDFP standard is based on cables made of 32 fibers. Having multiple fibers in parallel has obviously an impact on cable management and cable cost. In addition, connectors involving many fibers are susceptible to show a higher loss. For this reason, VCSEL based multi-wavelength links (coarse WDM) have been proposed. The acronym SWDM, standing for Shortwave Wavelength Division Multiplexing, has been recently introduced to distinguish this technology. To realize the multiplexing and demultiplexing operations, thin-film filters based solutions are among the most mature. Each thin film transmits a wavelength and reflects the others, at low loss in both cases. Such filters are cascaded to progressively isolate all wavelengths. Solutions to efficiently couple signals emitted by an array of VCSELs into optical fibers have also been investigated. Short-reach VCSEL based transceivers are expected to scale to 1 Tb/s bandwidth by means of highly fiber-parallel cables and/or WDM, in conjunction with high-speed signaling at or beyond 50 Gb/s. VCSELs have the important property to authorize testing at the wafer level, whereas other laser sources must generally be tested after dicing. They also show an emission aperture about three times larger, which greatly facilitates packaging. Altogether, these advantages allow VCSEL based links to show cost figures of a few dollars per Gb/s. This metric will be further scaled down by means of higher signaling speeds, increased wavelength and/or fiber parallelism, and as a result of further simplified packages and test procedures. Increase in manufacturing volumes should also drive the cost down.
4.3.2 Emerging Silicon Photonics Interconnect Technologies

Silicon photonics (SiP) emerged in the last decade as a promising optical interconnect technology. SiP takes advantage of the high index contrast between silicon (3.476 at 1550 nm) and silica (1.444 at 1550 nm) to enable micro-meter scale optical guiding structures such as add-drop filters and switches. For modulation, free-carrier dispersion effect is the only mechanism in silicon fast enough to enable purely silicon-based high-speed electro-optic modulation (10 Gb/s and beyond). Modulators are controlled by placing a PN or PIN region with typical doping levels on the order of 1017 1018 cm\(^3\) around the modulating structure. Combined with the resonant nature of ring resonators, compact wavelength-selective electro-optic modulators with very small footprint can be realized in SiP platforms \[27\]. An array of such modulators can provide WDM transmission with aggregate rates in the excess of 100 Gb/s. Modulation can also be realized in silicon alone by means of MachZehnder Interferometers (MZI). MZIs are less sensitive to thermal fluctuation than ring resonators, but are not wavelength selective, obliging each wavelength to be independently modulated before being multiplexed. Another modulation approach consists of selectively growing SiGe waveguides on top of a silicon wafer to form an electro-absorption modulator.

Unlike VCSELs that are directly modulated, a silicon photonic platform relies on modulators that imprint the desired information on a continuous wave light generated by an external laser. Due to its intrinsic material properties, Silicon is an extremely poor light emitter. Light generation and emission thus relies on lasing of other material systems (e.g. IIIV semi-conductors). The promise of using already advanced CMOS infrastructure for mass production of SiP is therefore challenged by the complexity of on-chip optical power generation. Co-packaging of an external laser with the SiP chip or flip-chip bonding are the solutions that have been already investigated. So far, however, no cost-efficient packaging solution has emerged. Packaging challenges must also be addressed with respect to the coupling of light from SiP chip to the single-mode fibers. Although single-mode fibers are cheaper than multi-mode fibers, their connection to the SiP chip via grating couplers or edge-couplers typically require accurate alignment to avoid high optical loss. This in turn adds an additional level of complexity to the overall packaging of SiP. This situation, in comparison, is much more relaxed for the connection of VCSELs to multi-mode fibers thanks to their considerably larger core diameter and to the wide aperture of VCSELs. Silicon photonics systems based on single-mode fibers support a much wider use of wavelength multiplexing than their VCSEL-based
counterparts. This potentially permits to amortize coupling-related packaging cost over larger link data-rates. The cost of the external optical power source can similarly be mitigated if a single laser capable of simultaneously emitting multiple wavelengths (comb laser) is used.

WDM operation can provide unprecedented interconnect bandwidths that fall well within the requirements of supercomputers in the near future. This concept was demonstrated by using a single quantum dot comb laser and an array of SiP ring modulators with 10 Gb/s per laser line. Based on this capability recent work on SiP-based DWDM interconnects showed the possibility of 1.56 Tb/s bandwidth at 25 Gb/s signaling rate and overall 7.5 pJ/bit consumption (assuming full link utilization) \[28\]. More recently, updated work showed a maximum aggregation of 2.1 Tb/s at 45 Gb/s per channel.

There are strong motivations to co-integrate the optical transceivers with compute modules (CMP or GPU), as well as with memory packages. A single package allows cost reduction for OEM vendors, reduces the wiring complexity on boards, results in higher component density, and most importantly can reduce signal degradation between data source and optical transceiver. If transceivers and data sources are placed in close proximity, their communication can be simplified and greater power and area saving can be achieved. In 2012 Altera together with Avago demonstrated an FPGA VCSEL transceiver assembly using a package on package (PoP) approach. The optical aggregate bitrate of the FPGA assembly reached 120 Gb/s. Recent packaging trends are aiming at a closer integration of transceivers and ICs within the same package. System in package products integrate several chips within one package by coupling them using a common interposer. The interposer will incorporate dc and transmission lines to interconnect all dice within the package. In the easiest case the dice are coupled to the interposer using wire bonds. Flip-chip assemblies are a prominent technique to connect high performance chips. It allows for very low parasitic connections between a data source and a transceiver in the same package. It becomes even more interesting if the underlying interposer is a silicon photonic chip, integrating modulators and receivers that are steered by the stacked chips.

A silicon photonic interposer enables optical networks in-package either for high bitrate communication of chips within the same package or at the same speed with peripherals as the package boundary is of no importance for optical signals. The highest level of integration is reached when the data source integrates optics on the same die, so called monolithic solutions. Monolithically integrated chips have the smallest parasitic loadings possible. Therefore, they show very high energy efficiencies. However, CMOS processes are not optimal for silicon photonic structures. In addition, optical structures cannot be arbitrarily reduced in size and a single modulator will stay several micro meters big. Hence, monolithic solutions are very costly if integrated with modern deep sub-micrometer CMOS processes. From a geometrical perspective it is a challenge to integrate a sufficient number of pins and transceivers into each die or package to carry all the data in and out. Both directly modulated VCSELs as well as silicon photonic transceivers can emit and receive light into and from fibers perpendicularly oriented to the chip plane. If a chip does not need to carry the data to the optical transceiver by a 2D interposer but instead can emit and receive on the top surface of the die or die stack itself, very high bitrate densities can be achieved, independent from the overall packaging approach.

To a large extent, but not completely, independent of how the electrical chip is interfaced with the optical transceivers is the connection of fibers or optical connectors to the optical transceivers. VCSELs can be directly coupled to multimode fibers. In this case the fiber is always perpendicular to the VCSEL and therefore to the package it is assembled upon. The advantage of multimode fibers is their large aperture which leads to high fabrication tolerance and passive alignment structures. If VCSELs are used for WDM to increase the bitrate per fiber, micro optical packaging needs to be employed. Micro optical packaging requires very high precision assemblies that are expensive.
to process. Because the structures on silicon photonic chips are much smaller, coupling light from an on-chip waveguide into a fiber is a challenge that leads to many solutions. Good coupling can only be achieved if the light mode (the phase and intensity distribution) is matched on chip to the mode inside common fibers.

**Technology Readiness Timeframe:** Research and development is pushing forward the forefront of silicon photonics design and manufacturing. Progressively, an ecosystem of fabrication infrastructures, circuit design and automation software (EPDAs), researchers and industries is emerging. In 2015, the US Department of Defense initiated a national center of innovation specifically dedicated to nanophotonic system manufacturing (AIM Photonics) [29]. However, without specific investment, the adoption of photonic technologies in high-performance (Exascale and beyond) interconnects over the next 5 years will largely build on the technologies currently developed for the commercial data center market where there is less emphasis on performance and energy efficiency.

There are also some preliminary results showing the promise for using photonics for going beyond communication to enable a new kind of analog computing. An example is the recent development of a new architecture for an optical neural network (NN) that could bring significant advantages in computing speed, latency, and energy consumption [30,31]. Recent experimental demonstrations show the core components of the architecture using a new class of fully programmable nanophotonic processor based on a CMOS-compatible silicon photonics architecture (see Figure 4.7). The key advantage for NNs is that the matrix transformation, which combines signals in neural networks, is performed optically at the speed of light. The number of operations needed to compute this transformation on N input signals scales linearly as N, whereas it scales as N^2 in a digital NN. In addition, the weight matrix – i.e., the strengths of connections between signals – can be encoded into a passive photonic circuit, whereas the digital NN requires the weight matrix to be accessed from memory. As a result, the optical NN promises significant advantages in speed and energy consumption.

### 4.4 Neuromorphic Computing

Neuromorphic computing covers a very broad set of approaches. In this section, we will give a brief overview and history to set the context, and we will highlight what are the most promising opportunities. Figure 4.5 shows a high-level comparison between conventional and neuromorphic computer architectures taken from a recent DOE report [32]. The data path between the CPU and the memory unit serves the as-called von Neumann bottleneck. In contrast, a neural network based architecture combines synapses and neurons into a fine grain distributed structure that scales both memory (synapse) and compute (soma) elements as the systems increase in scale and capability, thus avoiding the bottleneck between computing and memory.

Generally speaking, neuromorphic computing refers to the implementation in hardware of circuits emulating, whether closely, or remotely, the behavior of the brain, in particular neurons and synapses. We need to distinguish two main trends, and purposes, of neuromorphic computing: (1) emulating the behavior of a subset of the brain, i.e., a number of neurons, (2) achieving brain-like functionality, such as object or speech recognition, i.e., actual applications. Until recently, most of the funding and efforts were targeted at approach (1). Some of the main programs include DARPA Synapse in the US, and the Human Brain Project in Europe. They resulted in architectures by IBM, or the SpiNNaker architecture from University of Manchester, UK, capable of emulating a billion or more spiking neurons. The general spirit of such approaches is that such architectures can be used as modeling tools for neuroscientists; from a functionality perspective, there is an ex-
Figure 4.4: The optical NN consists of a series of \( n \) layers, each consisting of a matrix transformation \( M \) followed by an optical nonlinearity. The computation on an input vector \( \mathbf{X}_{\text{in}} \), encoded in the amplitudes of laser signals (left), occurs nearly instantaneously at the speed of light.

Figure 4.5: Comparison between conventional and neuromorphic computer architectures
pectation (and a bit of a stretch) that aggregating a large number of spiking neurons will lead to brain-like functionality. While the scientific value of such machines for neuroscience is a possibility, the approach hasn’t demonstrated significant successes in terms of functionality or efficiency. A key problem is that spiking neurons-based algorithms for actual tasks (e.g., object recognition) aren’t competitive, for now, with machine-learning algorithms based on deep neural networks.

Artificial neural networks, more recently coined Deep Neural Networks (DNNs), form approach (2). The principle of artificial neural networks is to use neurons which are only remotely similar to the brain neurons, essentially performing a sum of input neurons weighted by synapses, followed by a non-linear function. The history of artificial neural networks is complex, and their success only recent. After an initial excitement in the 1950s with the Perceptron, there was a spike of enthusiasm and interest with Multi-Layer Perceptrons (MLP) in the 1980s/1990s. Then, outperformed by algorithms with seemingly better properties, such as Support Vector Machines (SVM), they faded away. It’s only after GPUs allowed to train large enough networks with enough training data, that researchers were able to show how powerful these approaches are. Today, DNNs are at, or close to, human-level performance for non-trivial tasks such as object recognition, speech recognition, translation, etc. As a result of their growing popularity, it has become sensible for companies, such as Google, to implement ASICs to efficiently support such algorithms. Google has publicly disclosed using TPUs/Cloud TPUs in its data centers, Microsoft and Amazon have disseminated FPGAs for the same purpose, and NVIDIA is actively supporting the usage of DNNs in self-driving cars.

**Technology Readiness Timeframe:** Going forward, we can expect such algorithms to be broadly used, both in data centers, and in devices, from phones to self-driving cars, and many others, and as a result, many companies are expected to propose ASICs efficiently supporting them.

### 4.5 Quantum Computing

Quantum computing is a model of computation that proposes to exploit the quantum mechanical nature of specific physical phenomenon to provide advantage relative to so-called classical computing, i.e., the familiar use of CMOS and other digital logic. Whereas N digital bits contain one N-bit state, N entangled quantum bits (qubits) contain $2^N$ states upon which operations can be simultaneously applied. Quantum computing was originally conceived of as a way to use quantum mechanical phenomenon to solve problems in modeling other quantum mechanical properties of materials. The range of potential applications for which quantum computing offers advantages relative to classical computing has since expanded, including factoring composite integers (Shor), search (Grover), and optimization (quantum annealing). A complete list of known quantum algorithms and the speedups they offer can be found at [33].

Quantum computing today is a promising technological direction, but one that is still itself an object of research, and not yet a tool that can be applied for broader scientific discovery. Since the advent of Shors algorithm, there has been substantial investment in quantum computing Worldwide, first by governments, and more recently, commercial interests. These investments tend to be directed away from DOE SCs mission of scientific discovery, and hence there are many opportunities for DOE, and in particular, ASCR, to contribute.

Quantum speedups, i.e., algorithms with better scaling properties have been discovered for a variety of scientific problems of interest to DOE. These range from problems in chemistry and physics, to data analysis and machine learning, and to fundamental mathematical operations. The above-mentioned quantum algorithms are supported by theoretical proof of their scaling properties. However, without the existence of suitable quantum computers, they cannot yet be exploited to accelerate time to discovery. DOE SC (BES, others?) can work on the development
of materials and devices to make it possible to realize such machines in the future, at scales where they will offer true computational advantage relative to classical machines.

Prototypes of small quantum systems, be they specialized annealing devices, or even general purpose computers, are beginning to appear (D-Wave, IBM, etc.). DOE ASCRs facilities division can take a leading role in evaluating such devices, and making them accessible to the broader scientific community. Quantum computing systems need to be isolated form the external world, so as to maximize coherence. Helium-3 dilution refrigerators, inside of Faraday cages, are often used for thermal and electromagnetic isolation, as illustrated in Figure 5.6. As a result, there are fundamental challenges in creating quantum computing testbeds that go beyond the quantum substrate, e.g., a thermal hierarchy is needed to bridge the large thermal gradient across a host processor operating at an ambient temperature (300°K), a cryogenic control processor operating at 4°K and the quantum substrate operating (say) at 20 mK. However, while all quantum devices currently under development need these extreme levels of cooling, it may be possible in the future to create quantum devices that do need such cooling.

**Technology Readiness Timeframe:** Quantum computing is evolving from a theoretical curiosity in the 1980s to a tantalizingly close possibility today. Specialized devices, such as open system, adiabatic quantum annealers (D-Wave and soon QEO) are available today, but still have fundamental challenges to overcome before becoming useful (arXiv:1703.03871). General purpose machines, albeit with limitations on size and error correction, are also starting to appear (e.g., devices being developed by IBM), and it reasonable to expect that they will scale in the post Moores Law timeframe to be able to solve problems of interest to DOE, such as electronic state calculations.

If and when powerful quantum computers become available, capable of uniquely solving the nations problems in science and engineering, they may still remain unapproachable to the vast majority of scientists and engineers, who have not been trained to use them. Development of suitable programming languages and tools will need to accompany the systems themselves, in a way analogous to the development of such tools for classical computing, which started six decades ago with FORTRAN and continues today.
4.6 Analog Computing

Analog computing is the use of a physical process that is of reasonable efficiency to compute an analogous process that shares the same physical relationships. A simple example is the electronically-hydraulic analogy for Ohm’s law \[34\]. Electrical analogous systems are particularly well suited to solving (systems of) partial differential equations – an approach that was used extensively prior to the emergence of digital computers \[35\]. The success of digital was due to its ability to represent quantities to much higher dynamic range and precision than were then (and now) possible in analog electronics. There are several reasons for this, including the manufacturing process variations that impact the signal-to-noise ratio (SNR) and accuracy of differential amplifiers, and the limits of metrology even in the case of infinite SNR \[36\].

A second approach to analog computation is via modeling physical processes that naturally reconfigure themselves according to the theory of thermodynamics \[37\]–\[38\]. We believe this approach to analog computing holds great promise as well.

In its simplest form, a thermodynamic computer (TDC) is a system that uses the thermodynamics of annealing near equilibrium to find (near) optimal solutions to complex problems (e.g., D-Wave). Generalizing from this, we posit that a new generation of computers that spontaneously organize are now possible. These TDCs are open, non-equilibrium, thermodynamic systems that evolve their organization in response to the thermodynamics in the environment. Formalization of these ideas has emerged recently from work in non-equilibrium statistical physics and related fluctuation theorems \[39\]–\[42\]. As was the case with Darwinian evolution, the idea of thermodynamic evolution challenges many long-standing philosophical and technical assumptions in the field of computing and beyond. In this workshop we seek to engage a community of researchers to create an appreciation and description of the opportunity that can motivate research, collaboration and support.

A generalized TDC architecture is a networked fabric of thermodynamically evolvable cores (ECs) embedded in a reconfigurable network of connections. Energy is the language of the network and time-efficient communication is critical. It is the job of the entire system, both the network and the ECs, to move energy from inputs to outputs with minimal loss. Losses within the TDC create variations that cause reconfigurations to naturally occur.

A TDC can be programmed to solve a specific problem. The “problem” is defined by the structure of the energy / information in the environment. Programmers preconfigure some of the ECs to define constraints. Dissipation within the network creates fluctuations over many length and time scales and thereby search for solutions over a very large state space. Structure precipitates out of the fluctuating state and entropy production increases in the environment as free energy flows through the network and dissipation decreases.

The recent interest in data-driven science has led to the creation and adoption of a new generation of machine learning techniques that dont require the relatively high level of precision associated with classical scientific and engineering applications, such as the solution of PDEs. This is reflected in the addition of half-precision (16-bit) to the IEEE 754 floating point standard, and its implementation in new devices such as the Nvidia Volta GPU. For such applications, that do not need high precision and can perhaps tolerate modest errors, analog computing offers the possibility of much greater performance or energy efficiency. There are many possible physical phenomena that can be revisited in this regard (e.g., the use of arrays of resistors for multiplication and lenses for Fourier transforms), many of which include techniques in use before the emergence of general purpose digital computing.
4.7 Application Challenges

While the new hardware technologies discussed in this chapter provide many exciting opportunities for future science applications, there will undoubtedly be very significant challenges for science applications to leverage these technologies. As previously discussed in Chapter 3, previous technology transitions have forced the developers of scientific and engineering applications to explicitly exploit dramatically increasing levels of parallelism. The form of parallelism that is exploited evolves, to reflect contemporaneous HPC architectures, but the basic tenet has held true for the last five decades, since the introduction of vector mainframes. With the end of Dennard scaling, and the cessation of clock frequency growth, increased capability now comes from exponentially increasing parallelism, and developers have to uncover these levels of parallelism in the algorithms, explicitly represent it, and then choreograph the interaction of millions of independent threads of computation. This is a daunting task today, and will only grow as we transition to exascale, where the number of independent threads will increase to be on the order of billions. The challenges abound, and there is need for mathematical and computer science research to address them, so as to make post-exascale systems accessible to as broad a swath of the computational science community as possible. We are already faced with the challenges of design for adaptability, heterogeneity, dynamic data and work partitioning, and remote and asynchronous execution. Looking to the future, there are also the core challenges of designing scientific applications for reconfigurable logic, memory centric and silicon photonics technologies (among others).

It is anticipated that exascale systems will have $O(10^9)$ ALUs, and perhaps $O(10^{10})$ threads. The parallelism needed to go beyond exascale will surely be even greater. Research into mathematical algorithms that can both create and sustain this level of parallelism, without excessive synchronization is critically needed. Simple operations in familiar algorithms, like computing residuals or Courant numbers threaten to become computational bottlenecks due to the need to coordinate their computation amongst all processors. New algorithms that scale effectively, yet are also robust enough to solve a broad range of problems need to be invented.

Mapping new or existing applications to post-exascale and post-Moore computing systems will be increasingly challenging. As discussed in this chapter, increasingly heterogeneous components will be incorporated into systems, to maximize both computing power and energy efficiency. Choosing among the diverse components of one computing environment will be challenging, and porting amongst multiple such systems even more so. New execution models will need to be created, with abstractions for components that we do not have today, e.g., quantum-based accelerators and ephemeral FPGA-based functional units. Programming systems will need to assist developers face these application challenges by creating and mapping new programming abstractions to diverse machine, and providing tools for both functional and performance debugging that allow users to understand if their programs are running correctly, and with adequate performance, and where to fix them when they are not.

Finally, quantum and analog computing represent qualitatively different approaches from the other technologies, and it is difficult to predict at this time if and how applications for these technologies will be integrated into our HPC ecosystem. At the same time, these technologies are presently highly specialized, and their application base will likely start small, so concerns of integration are not pressing.
4.8 Open Platforms

As increasingly diverse hardware architectures proliferate, co-exist, and interact with traditional instruction set architectures, there is an increased need for the development of open platforms with open interfaces. Some of the key issues to be addressed by open interfaces include:

- resource allocation, protection, and coordination,
- efficient management of multiple memory domains with varying characteristics,
- memory address translation management,
- cache management optimizations,
- extreme scale file and storage system demands, and
- security in the presence of "bare metal" directly attached and network-accessible collections of accelerators.

On the hardware front, these open interfaces could help support the development and integration of new hardware protocols for communication, coherence, and synchronization among processing units, as well as novel, tightly integrated accelerators/co-processors, some of which may be the outcome of open source hardware development. On the software front, open interfaces could enable new innovations in system software to support both distributed computations as well as distributed data stores to hold the growing experimental and observational science data.

As a recent example of the benefits of open interfaces, we can look at the tremendous success in identifying and designing new scientific software abstractions and libraries that make the use of neuromorphic platforms almost turnkey for application developers. Open source software libraries such as TensorFlow, Caffe, and others [43] have enabled many scientists to integrate machine learning into their computational workflows. The emerging importance and the growing hardware support for fast low-precision computations has spurred a new effort for batched and low precision BLAS [44]. All of these developments are being integrated seamlessly into our computing ecosystem.
Chapter 5

Findings

5.1 Need for clarity in future HPC roadmap for science applications

The challenges associated with post-exascale and post-Moore computing are receiving significant attention from multiple government agencies and initiatives including DARPA, IARPA, NSF and NSCI. However, while some of these efforts are focused on particular application domains (e.g., high-performance data analytics) there is currently a lack of clarity as to what the future high performance computing roadmap is for science applications. The subcommittee believes that Science will need to prepare for a period of uncertainty in future HPC technologies and computing paradigms, akin to the uncertainty of the 1990s before our current Massively Parallel Processing (MPP) paradigm emerged as dominant successor to vector parallelism. However, it is exactly because of this uncertainty that there is a need to focus on strategy and planning activities so as to better anticipate what the future HPC roadmap possibilities will be for science applications.

5.2 Extreme heterogeneity with new computing paradigms will be a common theme in future HPC technologies

As discussed in Chapter 4 there is a great diversity in the technologies that are expected in the post-exascale and post-Moore eras. These technologies include new forms of heterogenous processors, heterogeneous memories, near-memory computation structures, new interconnect technologies (including silicon photonics), and non-von Neumann computing elements based on analog, neuromorphic and quantum technologies. This diversity in computing paradigms has been appropriately labeled as “extreme heterogeneity” in an upcoming ASCR workshop and related discussions. The subcommittee believes that there is value in focusing on extreme heterogeneity as a common theme in future HPC technologies, so as to enable a broader view of post-Moore computing rather than focusing solely on point solutions such as neuromorphic computing and quantum computing. At the same time, there are compelling research challenges in moving these point solutions forward so that they can be integrated in future platforms that exhibit extreme heterogeneity.
5.3 Need to prepare applications and system software for extreme heterogeneity

As discussed in the report, different applications have responded to past technology transitions (e.g., from vector to MPP, terascale to petascale, petascale to exascale) in different ways. We are rapidly approaching a period of significant redesign and reimplementation of applications that is expected to surpass the disruption experienced by the HPC community when transitioning from vector to MPP platforms. As a result, scientific teams will need to prepare for a phase when they are both using their old codes to obtain science results while also developing new application frameworks based on the results of applied math and computer science research investments that need to be made now.

5.4 Need for early testbeds for future HPC technologies

Given the wide diversity of technologies expected in the post-Moore era, accompanied by radically new computing paradigms in many cases, there is a need for building and supporting early testbeds for future HPC technologies that are broadly accessible to the DOE community, so as to enable exploration of these technologies through new implementations of science (mini-)applications, e.g. [45]. These explorations could also yield new computational motifs that are better aligned with the new computing paradigms. There are multiple instances of individual research groups at DOE laboratories creating early testbeds (e.g., [46–49], but administration of such testbeds is necessarily ad hoc and lacks the support for broad accessibility that is typical for DOE computing facilities. Collaborations between DOE laboratories and universities (e.g., [50]) can help improve accessibility, but still not at the scale of infrastructure supported by DOE laboratories.

5.5 Open hardware promises to be a major trend in future platforms

With extreme heterogeneity, there is a growing trend towards building hardware with open interfaces so as to integrate components from different hardware providers. The motivation behind this trend is to enable new approaches to System-on-Chip (SoC) design that can more easily integrate components from different vendors.

There is also a growing interest in building “open source” hardware components through recent movements such as the RISC-V foundation. Despite many obstacles in building production-strength hardware components through an open source approach (e.g., lack of EDA tools that are used for building proprietary hardware), open source hardware promises to be a growing trend in the future, which could help support the creation of hardware components (e.g., on-chip accelerators and interconnects) that are customized to the needs of science while being integrated with proprietary components from hardware vendors. For the purpose of this report, the term “open hardware” encompasses both open interfaces for proprietary components as well as open source hardware.

5.6 Synergies between HPC and mainstream computing

Though this report has focused on future high performance computing requirements from the perspective of science applications, there are notable synergies between future HPC and mainstream computing requirements. Some of them have been called out in the paragraphs on Technology
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Readiness for the different technologies described in Chapter 4 e.g., there is already a growing commercial use of reconfigurable logic in mainstream platforms. One application area where these synergies are already being leveraged, and will undoubtedly grow in the future, is in the area of data-intensive applications and data analytics (e.g., the use of neuromorphic computing and other accelerators for deep learning). As observed in a past ASCAC study, there are also notable synergies between the data-intensive computing and high-performance computing capabilities needed for science applications.
Chapter 6

Recommendations

6.1 Office of Science’s Role in Future HPC Technologies

Recommendation 1: The DOE Office of Science should play a leadership role in developing a post-Moore strategy/roadmap/plan, at both the national and international levels, for high performance computing as a continued enabler for advancing Science.

The findings in this study have identified the urgency of developing a strategy, roadmap and plan for high performance computing research and development in the post-exascale and post-Moore eras, so as to ensure continued advancement of Science in the future. Though there are multiple government agencies that are stakeholders in post-Moore computing, the subcommittee recommends that the DOE Office of Science play a leadership role in developing a post-Moore strategy/roadmap/plan for advancing high performance computing in the service of Science. As in past years, this leadership role should span both the national and international levels.

There are many aspects to leadership in this regard. As was done for exascale computing, it is important for DOE to raise public awareness of the upcoming post-Moore challenges, and its impact on different science domains, well in advance of the start of the post-Moore era. However, unlike exascale computing, it will also be important to set expectations that different post-Moore technologies will have different time horizons, which will require a more agile and adaptive planning methodology than is being followed in the Exascale Computing Project. In addition, engagement with existing technology roadmap efforts (such as IRDS) should play a key role in establishing DOE’s strategy as to which timeframes are appropriate for adopting different post-Moore technologies. Finally, international competitiveness dictates that DOE Office of Science maintain its role in ensuring USA’s continued worldwide leadership in high performance computing.

6.2 Investing in Readiness of Science Applications for post-Moore era

Recommendation 2: DOE should invest in preparing for readiness of science applications for new computing paradigms in the post-Moore era

The findings in this study have identified the challenges involved in preparing applications for past technology disruptions, and the fact that these disruptions will require exploration of new computing paradigms as we move to extreme heterogeneity in the era of post-Moore computing. The subcommittee recommends that the Office of Science, work with other offices of DOE to ensure that sufficient investment is made with adequate lead time to prepare science applications for the post-Moore era. While the adaptations that ECP application teams are starting to make
for supporting current and emerging heterogeneous execution environments is good preparation for some of the anticipated post-exascale technologies, additional investments will be needed to explore the newer computing paradigms that will emerge in the post-exascale and post-Moore timeframes.

There are multiple dimensions to investing in the readiness of science applications. First, preparing applications for new computing paradigms will be critical in the post-Moore era. It is observed that, while the Exascale Computing Project (ECP) has been structured to achieve the important goal of delivering an exascale system early in the next decade, it has also dampened efforts to explore the new paradigms that will be necessary for post-exascale and post-Moore computing. This dampening was intensified as the ECP delivery timeline was recently reduced by several years, and there is additional risk that pressure to deliver to the deadline will further narrow research exploration as part of ECP efforts. Thus, investing in application readiness will also require renewed investments in research in the areas of applied mathematics (e.g., exploring new models of computer arithmetic) and algorithms, which in turn will need to be tightly coupled with the development of new computation and data models in different science domains that will be necessary for the new computing paradigms. Second, this investment will require continued partnership between the Office of Science and other DOE offices, as is done in SciDAC and other joint programs. Third, a clear methodology will need to be established for making migration vs. rewrite decisions for different applications in different timeframes, as new technologies are adopted. Finally, the Office of Science should invest in organizing early workshops on post-Moore application readiness, as was done for exascale application readiness.

6.3 Investing in Research related to Open Hardware Platforms

**Recommendation 3:** DOE should invest in research to help foster an open hardware ecosystem as part of the future HPC technology roadmap

The findings in this study have identified the need for creating a more open hardware ecosystem in the post-exascale and post-Moore eras, relative to current and past approaches for hardware acquisition. In the interest of future Science needs, the subcommittee recommends that the Office of Science foster this ecosystem by investing in research related to open hardware platforms, i.e., platforms built using open interfaces that support high-performance and reliable integration of components from different hardware providers.

There are many reasons behind this recommendation. First, post-Moore hardware will require more innovation and agility in hardware design than in past decades, and an open platform approach will help foster this innovation while also mitigating risks associated with selecting a single vendor for hardware acquisition. There is a long history of DOE-sponsored research influencing industry hardware standards, and it is reasonable to expect that DOE’s investment in this research will in turn influence future standards for open hardware platforms. Second, the trend towards extreme heterogeneity in post-Moore computing reinforces the importance of integrating hardware components developed by different hardware providers. While these components will continue to be proprietary in many cases, it will be important to allow for the possibility of also integrating open source hardware components where appropriate. (The subcommittee recognizes that there are many obstacles to enabling the use of open source hardware components in production systems, but also sees an analogy here with the early skepticism to the use of open source software components that are now commonplace in production systems.) Finally, research investment is necessary because existing approaches to open interfaces are highly impoverished in both performance and reliability; new approaches are needed to overcome these limitations so as to ensure that leadership-class HPC hardware can be built for future science applications by tightly integrating
6.4 Investing in Research related to System Software

Recommendation 4: DOE should invest in research to help advance system software technologies to support post-Moore computing

The findings in this study have identified the need for advancing system software to meet the requirements of post-Moore computing. In the interest of future Science needs, the subcommittee recommends that the Office of Science ensure this advancement by investing in research related to open source and proprietary system software for future HPC technologies. In terms of synergies with mainstream computing, many of the system software capabilities needed to map science applications on future HPC systems will also be beneficial to commercial computing. The DOE should support active and sustained efforts to contribute to relevant software projects to ensure that HPC concerns such as performance isolation, low latency communication, and diverse wide area workflows are addressed in the design and adoption of system software for future HPC platforms.

There are many reasons behind this recommendation. First, over the past decades, DOE investments have helped ensure a successful history of using advances in system software to enable production DOE applications to run on leadership HPC systems. However, the current system software stack are built on technology foundations that are more than two decades old, and are ill-prepared for the new computing paradigms anticipated in post-Moore computing, e.g., new storage technologies to hold the ever-increasing experimental and observational science datasets, tighter integration of accelerators and co-processors than in the past, and new hardware consistency models for communication, coherence, and synchronization among different hardware components. Second, the combination of open hardware platforms and open source system software will enable software/hardware co-design to occur with the agility needed in post-Moore timeframe. Finally, system software has a longer history of reducing the impact of hardware disruptions on application software, and this role will be even more important in the context of future HPC technologies.

6.5 Early Testbeds in DOE Computing Facilities

Recommendation 5: DOE computing facilities should prepare users for post-Moore computing by providing and supporting early access to testbeds and small-scale systems

The findings in this study have identified the need for providing users of DOE computing facilities early access to testbeds and small-scale systems that are exemplars of systems expected in the post-Moore computing roadmap. The subcommittee recommends that the Office of Science’s computing facilities address this need by acquiring such testbeds and small-scale systems, and providing and supporting access to these systems by current HPC users. This recommendation is synergistic with the conclusions of a recent ASCR workshop on facility requirements for supporting computer science research [5].

There are multiple facets to this recommendation. The acquisition of such testbeds will require building relationships with hardware providers who are exploring new post-Moore technologies, some of whom may not have had past relationships with DOE facilities. The subcommittee believes that creating these new relationships will help foster a broader ecosystem of partners for future HPC systems. Further, to address the need for educating HPC users on future technologies, the support for these testbeds will need to extend beyond system support, and also include training, workshops, as well as fostering of user groups for different systems. The subcommittee also recognizes that labor costs (personnel, training, etc.) will be a more significant fraction of the cost of deploying a
testbed small-scale system, relative to the labor cost fraction in leadership facilities, but believes that this human investment is important for recruiting, growing and retaining talent (as discussed in the next recommendation). Finally, the subcommittee understands that this recommendation for DOE facilities must not distract from current exascale commitments, and trusts that investment in small-scale future HPC testbeds will be possible in the pre-exascale timeframe, with the goal of increased investments in this direction in the post-exascale era.

6.6 Recruiting, Growing and Retaining Talent for post-Moore era

Recommendation 6: Recruit and grow workforce members who can innovate in all aspects of mapping applications onto emerging post-Moore hardware, with an emphasis on recognizing top talent in this area.

The findings in this study have identified the need for significant innovation in support of the enablement of science applications on post-Moore hardware. The subcommittee recommends that DOE national laboratories prioritize the recruiting and nurturing of top talent in all aspects of mapping applications onto emerging post-Moore hardware, including skills and talent related to development of science applications, applied mathematics research, system software research, and hardware research for future platforms.

The context for this recommendation lies in observations that have been made in past ASCAC studies with respect to the increasing challenge of retaining talent in computing-related areas, give their high demand in the commercial sector. This challenge will continue to increase as companies start to develop their post-Moore computing strategies. However, the subcommittee believes that DOE national laboratories have unique opportunities to build a talent pipeline in this area, because it is expected that the DOE labs will explore post-Moore technologies in an earlier timeframe than many industry labs, which can be attractive to technical personnel who are passionate about working with cutting-edge technologies. Building the necessary workforce pipeline will require prioritization of post-Moore technologies in all avenues related to recruiting, growth and retention, including CSGF fellowships, postdoctoral appointments (including prestigious named postdoctoral fellowships), LDRD-funded projects, and recognition (through awards and other channels) of top talent in this area. In addition, building partnerships in post-Moore technology areas with interested and qualified faculty members in academia through established mechanisms, such as recruiting their students for internships, hosting them for sabbaticals, and joint faculty appointments, can further help with strengthening the talent pipeline that will be needed in DOE laboratories in the post-Moore era.
Chapter 7

Conclusions

This report reviewed opportunities and challenges for future high performance computing capabilities, with a focus on the use of computing for the advancement of Science. The review drew from scientific publications, presentations, reports and expert testimony. The report includes key findings and recommendations from the perspective of the post-exascale and post-Moore timeframes. While the subcommittee appreciated the timeliness of the charge, we acknowledge that a single study cannot provide a comprehensive answer to identifying research opportunities and challenges for future HPC capabilities in the post-exascale and post-Moore timeframes, which span multiple decades, and trust that there will be follow-on studies to elaborate further on these challenges and opportunities as details of emerging HPC technologies become clearer in the coming years.

An overarching concern that emerged from the subcommittee’s findings and recommendations is that DOE has lost considerable momentum in funding and sustaining a research pipeline in the applied math and computer science areas that should have been the seed corn for preparing for these future challenges, and it is therefore critical to correct this gap as soon as possible. While the subcommittee understands the paramount importance of DOE’s commitment to deliver exascale capability, it is also critical to fund research and development that look beyond the ECP time horizon. The recommendations in this report highlight areas of research and emerging technologies that need to be given priority in this regard (application readiness, open hardware platforms, system software), as well as supporting activities that are essential for success (post-Moore strategy leadership, early testbeds in DOE facilities, and recruitment, growth and retention of top talent in post-Moore technology areas).
Appendix A

Charge to Subcommittee

Department of Energy
Office of Science
Washington, DC 20585

Office of the Director

Professor Daniel A. Reed, Chair of the ASCAC
Office of the Vice President for Research and Economic Development
University of Iowa
2660 UCC
Iowa City, Iowa 52242

Dear Professor Reed:

Thank you for your continued service to the Office of Science (SC) and the scientific communities that it serves as the Chair of the Advanced Scientific Computing Advisory Committee (ASCAC). Your reports and recommendations continue to help us improve the management of the Advanced Scientific Computing Research (ASCR) program.

As you know, physical limitations are forcing an end to “Moore’s Law” which predicts a doubling of transistors every two years. Science relies on computing in so many ways, we must prepare for the significant changes ahead without wavering from our commitment to deliver exascale capability.

By this letter, I am charging the ASCAC to form a subcommittee to review opportunities and challenges for future high performance computing capabilities. Specifically, we are looking for input from the community to determine areas of research and emerging technologies that need to be given priority. ASCAC should gather, to the extent possible, input from a broad cross-section of the stakeholder communities.

To inform ASCR planning, I would appreciate receiving the committee’s preliminary comments by the Summer 2017 meeting, and a final report by December 20, 2017. I appreciate ASCAC’s willingness to undertake this important assignment.

If you or the subcommittee chair have any questions, please contact Christine Chalk, Designated Federal Official for ASCAC at 301-932-5152 or by e-mail at christine.chalk@science.doe.gov.

I appreciate ASCAC’s willingness to undertake this important activity.

Sincerely,

C. A. Murray
Director, Office of Science
Appendix B

Subcommittee Members

The ASCAC Subcommittee on Future High Performance Computing Capabilities consisted of the following members:

- Keren Bergman, Columbia University, ASCAC member.
- Tom Conte, Georgia Institute of Technology.
- Al Gara, Intel Corporation.
- Maya Gokhale, Lawrence Livermore National Laboratory.
- Mike Heroux, Sandia National Laboratories.
- Peter Kogge, University of Notre Dame.
- Bob Lucas, Information Sciences Institute.
- Satoshi Matsuoka, Tokyo Tech., ASCAC member.
- Vivek Sarkar, Georgia Institute of Technology, ASCAC member (subcommittee chair).
- Olivier Temam, Google.
Appendix C

Bibliography


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